

Improving High-Resolution Tropical Cyclone Prediction Using a Unified GSI-based Hybrid Ensemble-Variational Data Assimilation System for HWRF



Xuguang Wang
xuguang.wang@ou.edu
University of Oklahoma, Norman, OK

with

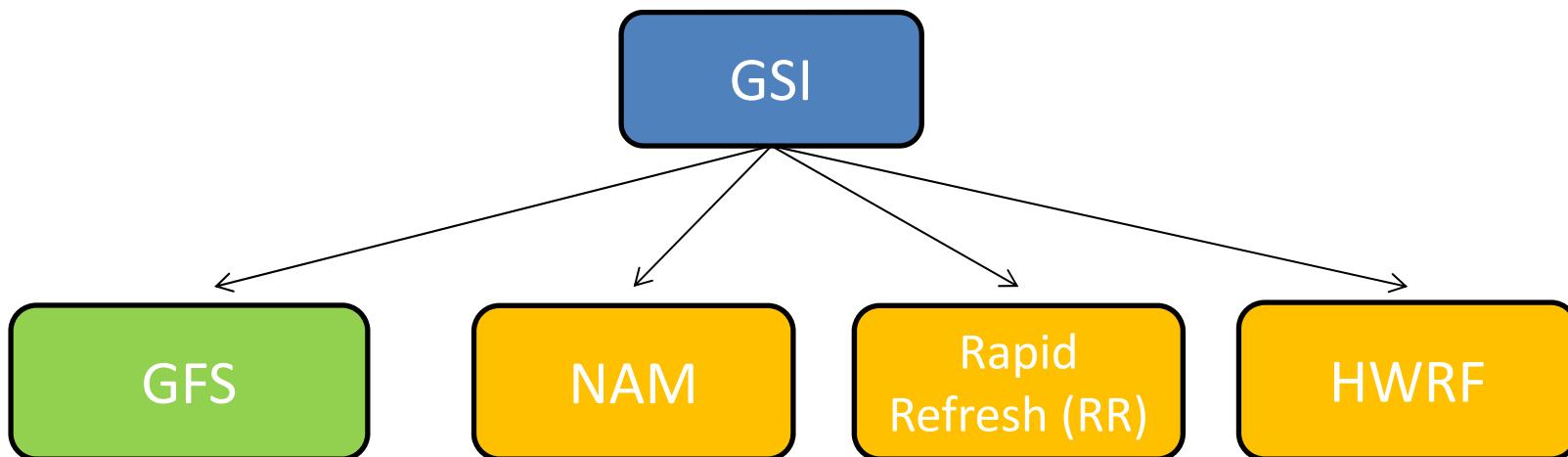
Xu Lu (OU), Yongzuo Li (OU), Mingjing Tong (NCEP), Jeff Whitaker (ESRL), Henry Winterbottom (ESRL), Ming Xue (OU) and many other HFIP DA teammates from NCEP, ESRL, HRD, DTC

HFIP first year review, July 10, 2013



Background

- The GSI-based hybrid DA system showed significant improvement for global forecast compared to GSI 3DVAR and became operational on May 22, 2012 for Global Forecast System (GFS).
- GSI is a unified system which provides data assimilation for all operational global and regional forecast system.





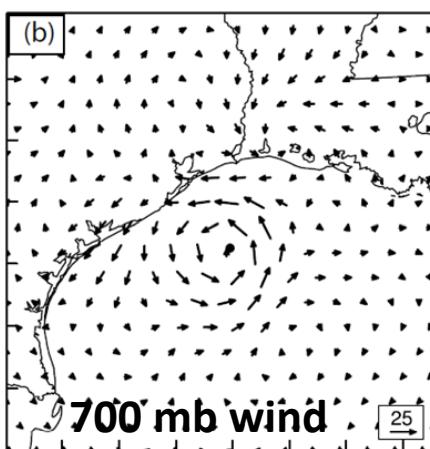
Background

- Efforts are being conducted to integrate the same GSI-based hybrid DA system with operational regional forecast systems.
- Unifying GSI-based hybrid DA system with operational regional systems facilitates faster transition to operations.
- The focus of the project is the extension, application, testing and research of the GSI-based hybrid data assimilation for the HWRF modeling system at high resolutions.
- Also motivated by encouraging results of ensemble based data assimilation for tropical cyclones.

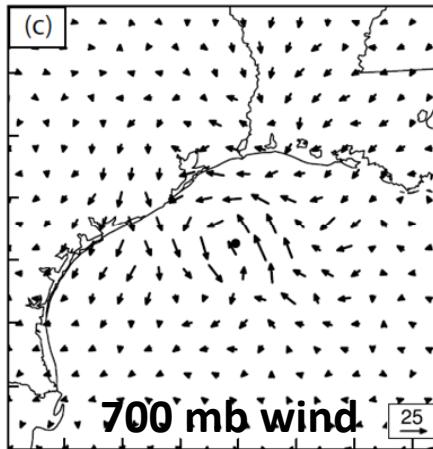


Background

3DVAR



hybrid



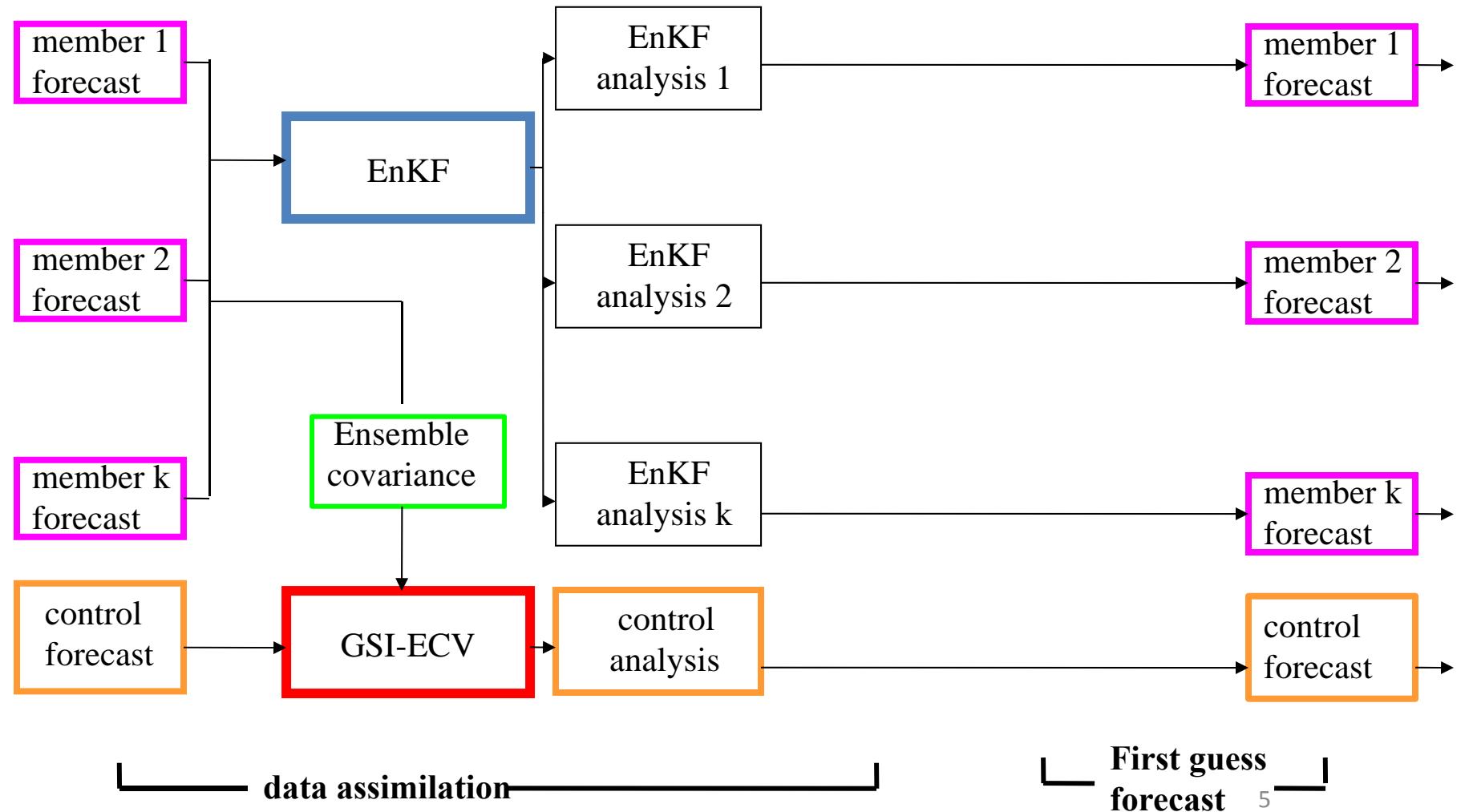
- Hurricane Ike 2008
 - WRF ARW: $\Delta x = 5\text{ km}$
 - Observations: radial velocity from two WSR88D radars (KHGX, KLCH)
 - WRFVAR hybrid DA system (Wang et al. 2008ab, MWR)

Li et al., 2012, MWR



GSI-based Hybrid ensemble-VAR DA system

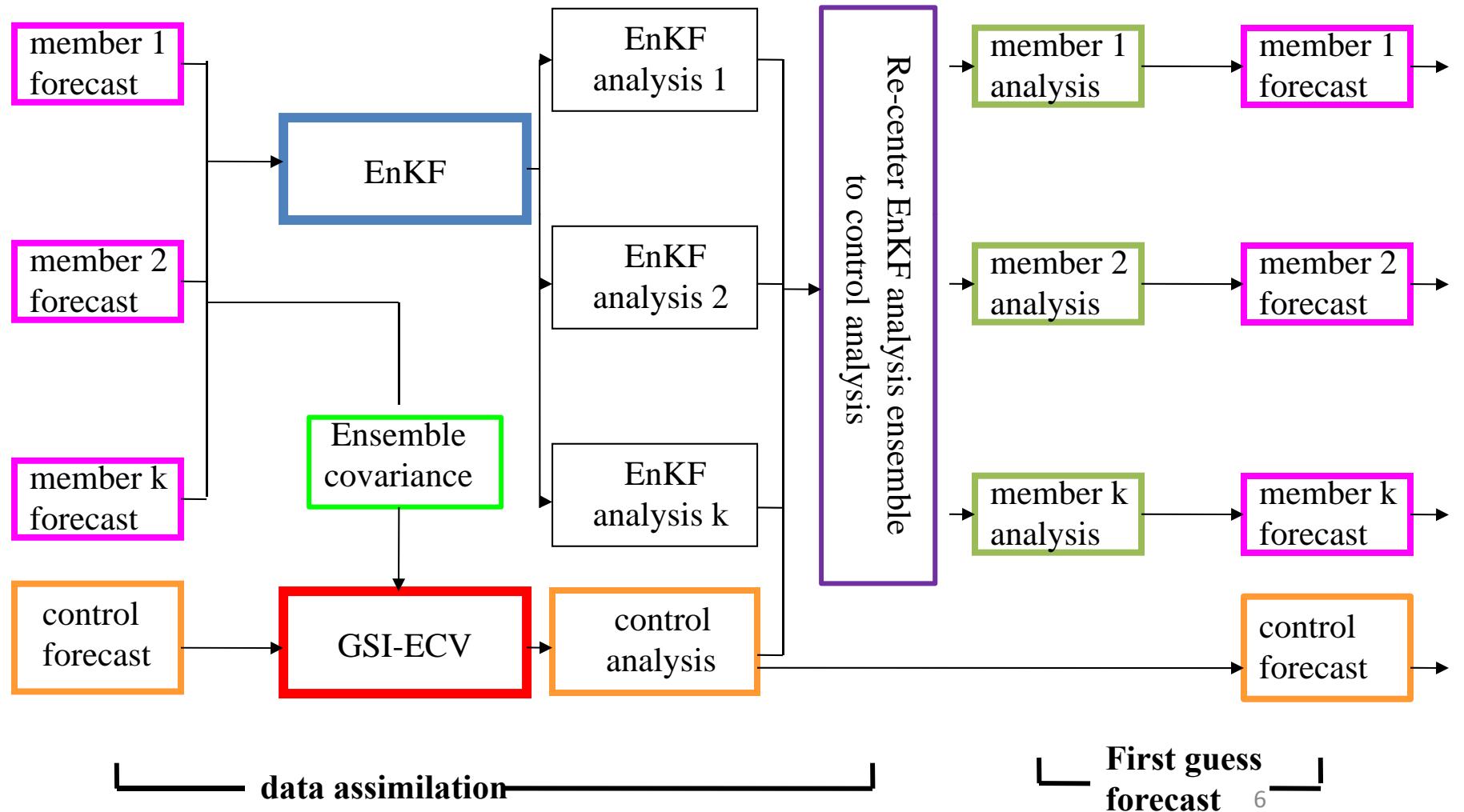
1-way coupling





GSI-based Hybrid ensemble-VAR DA system

2-way coupling





GSI-based hybrid ensemble-variational DA system

- **GSI-ECV:** Extended control variable (ECV) method (Wang 2010, MWR):

$$\begin{aligned} J(\vec{\mathbf{x}}_1, \vec{\mathbf{a}}) &= \beta_1 J_1 + \beta_2 J_e + J_o \\ &= \beta_1 \frac{1}{2} \vec{\mathbf{x}}_1^T \mathbf{B}^{-1} \vec{\mathbf{x}}_1 + \beta_2 \frac{1}{2} \vec{\mathbf{a}}^T \mathbf{C}^{-1} \vec{\mathbf{a}} + \frac{1}{2} (\vec{\mathbf{y}}^{o'} - \mathbf{H} \vec{\mathbf{x}}')^T \mathbf{R}^{-1} (\vec{\mathbf{y}}^{o'} - \mathbf{H} \vec{\mathbf{x}}') \end{aligned}$$

Extra term associated with extended control variable

$$\vec{\mathbf{x}}' = \vec{\mathbf{x}}_1' + \sum_{k=1}^K (\vec{\mathbf{a}}_k \circ \vec{\mathbf{x}}_k^e)$$

Extra increment associated with ensemble

- **EnKF:** square root filter interfaced with GSI observation operator (Whitaker et al. 2008, MWR)



System development and enhancement

- Develop interface to integrate both EnKF and GSI-ECV components with HWRF; different from H213 where ensemble is provided from GFS ensemble.
- Add/enhance inner core airborne radar data assimilation capability
- Enhance dual resolution assimilation capability
- Development/enhancement for GSI-ECV and airborne radar data have been transitioned into 2013 operational HWRF (H213)



Why Hybrid? “Best of both worlds”

Summarized in Wang 2010, MWR

	VAR (3D, 4D)	EnKF	Hybrid	References (e.g.)
Benefit from use of flow dependent ensemble covariance instead of static B		Yes	Yes	Hamill and Snyder 2000; Lorenc 2003; Wang et al. 2007ab, 2008ab, 2009; Buehner et al. 2010ab; Wang 2011, Zhang and Zhang 2012, etc.
Robust for small ensemble or large model error			Yes	Wang et al. 2007b, 2009; Buehner et al. 2010b
Better localization for integrated measure, e.g. satellite radiance; radar with attenuation			Yes	Campbell et al. 2010
Flexible to add various dynamical/physical constraints	yes		Yes	Wang et al. 2013
Use of various existing capabilities in VAR (e.g., Outer loops to treat nonlinearity; Variational QC)	yes		Yes	



Test with Hurricane Sandy, Oct. 2012

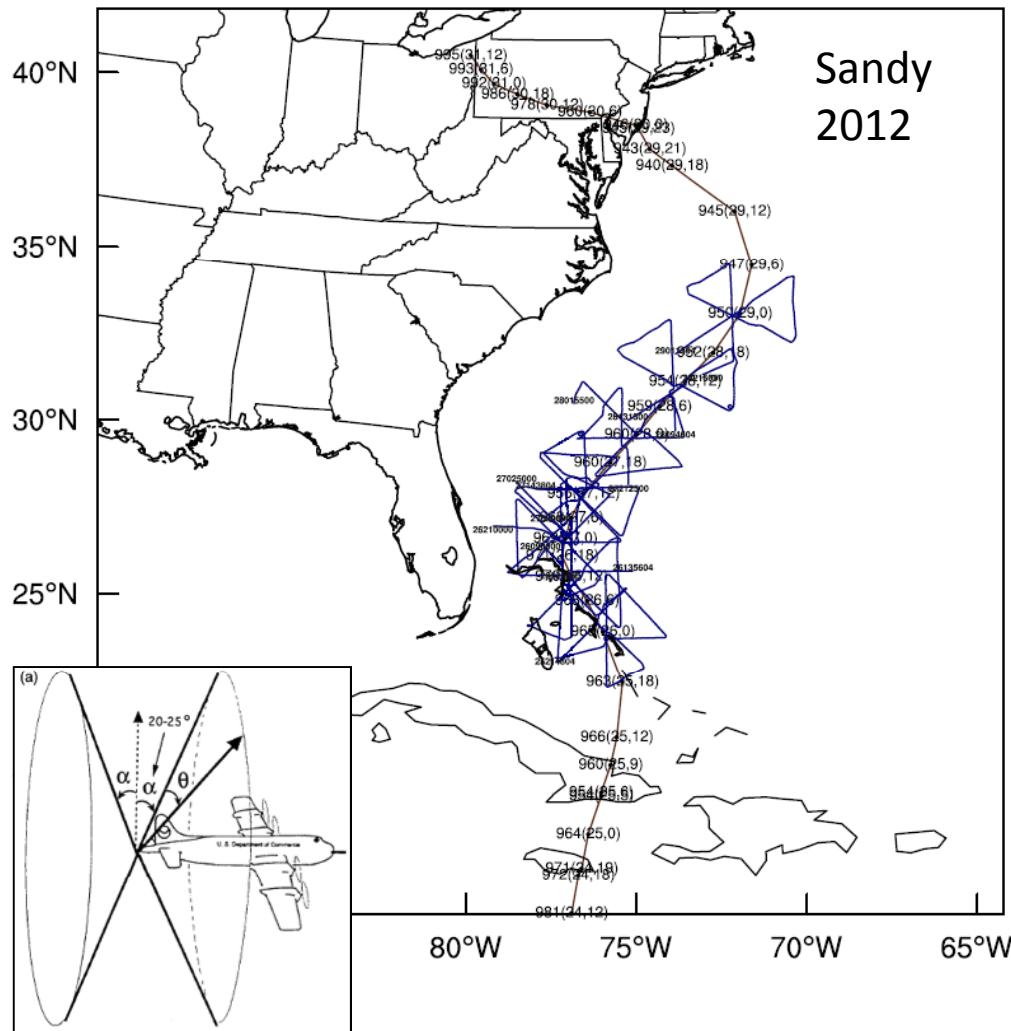


- Complicated evolution
- Tremendous size
- 147 direct deaths across Atlantic Basin
- US damage \$50 billion

New York State before and after
nhc.noaa.gov



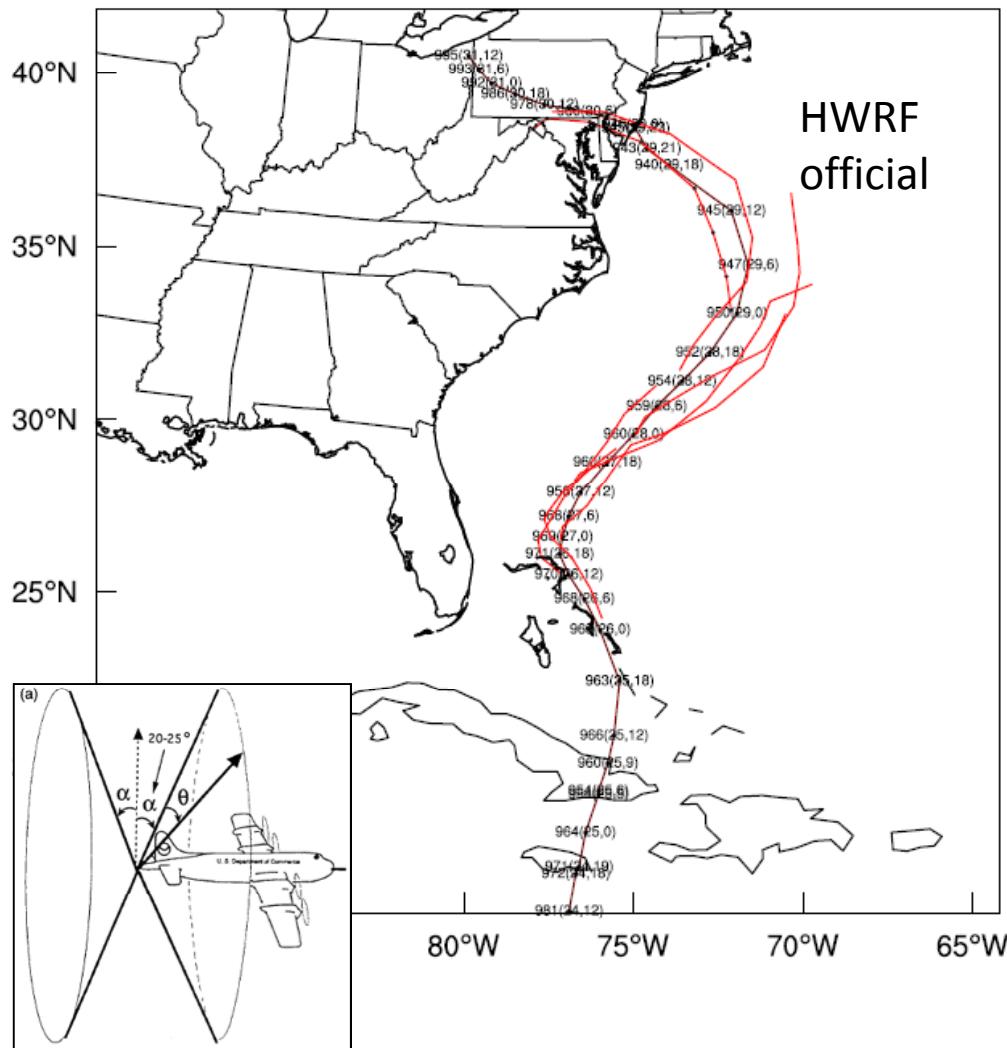
Experiment Design



- Model: HWRF
- Observations: radial velocity from Tail Doppler Radar (TDR) onboard NOAA P3 aircraft
- Initial and LBC ensemble: GFS global hybrid DA system
- Ensemble size: 40



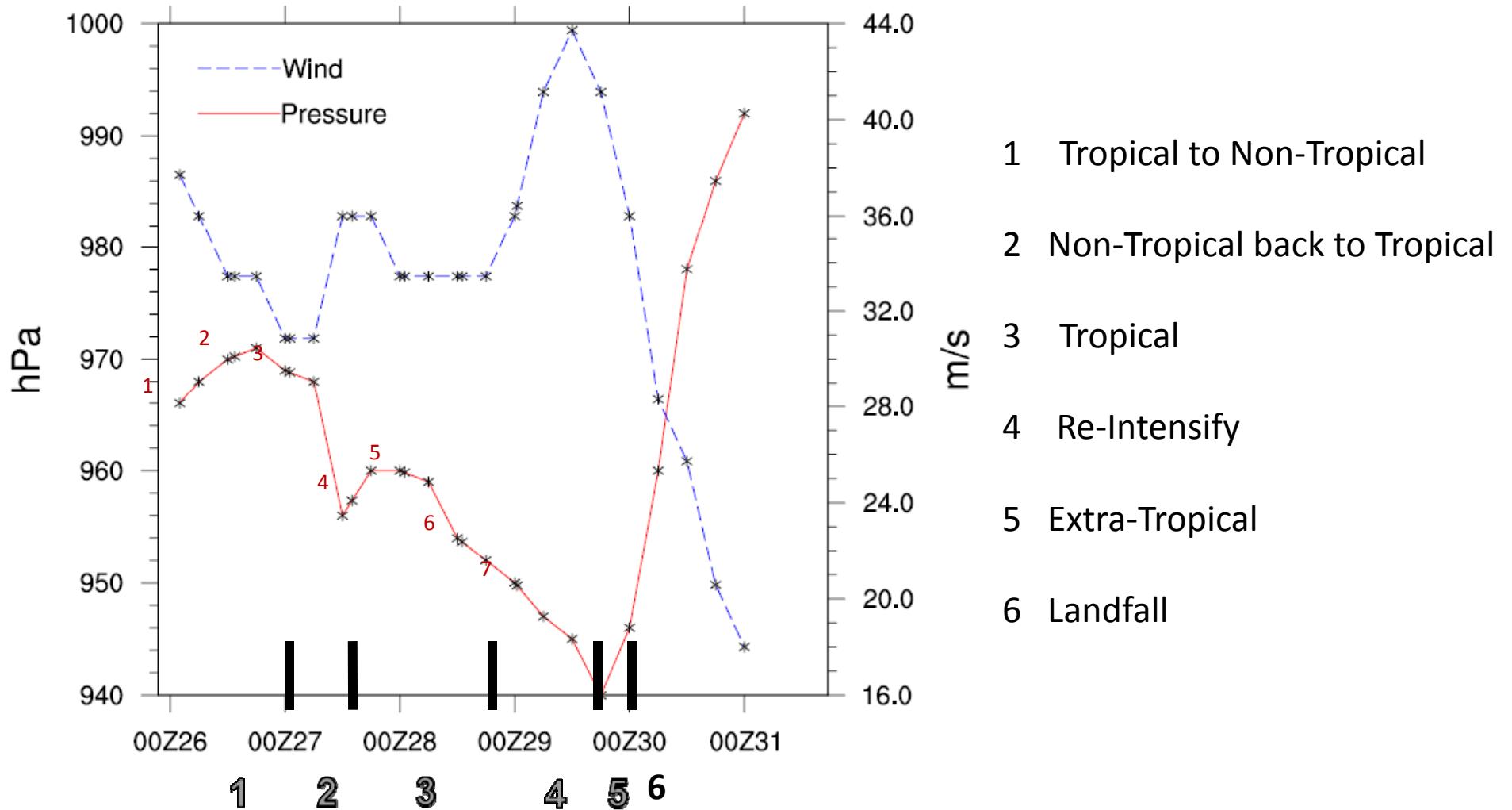
Experiment Design



- Model: HWRF
- Observations: radial velocity from Tail Doppler Radar (TDR) onboard NOAA P3 aircraft
- Initial and LBC ensemble: GFS global hybrid DA system
- Ensemble size: 40

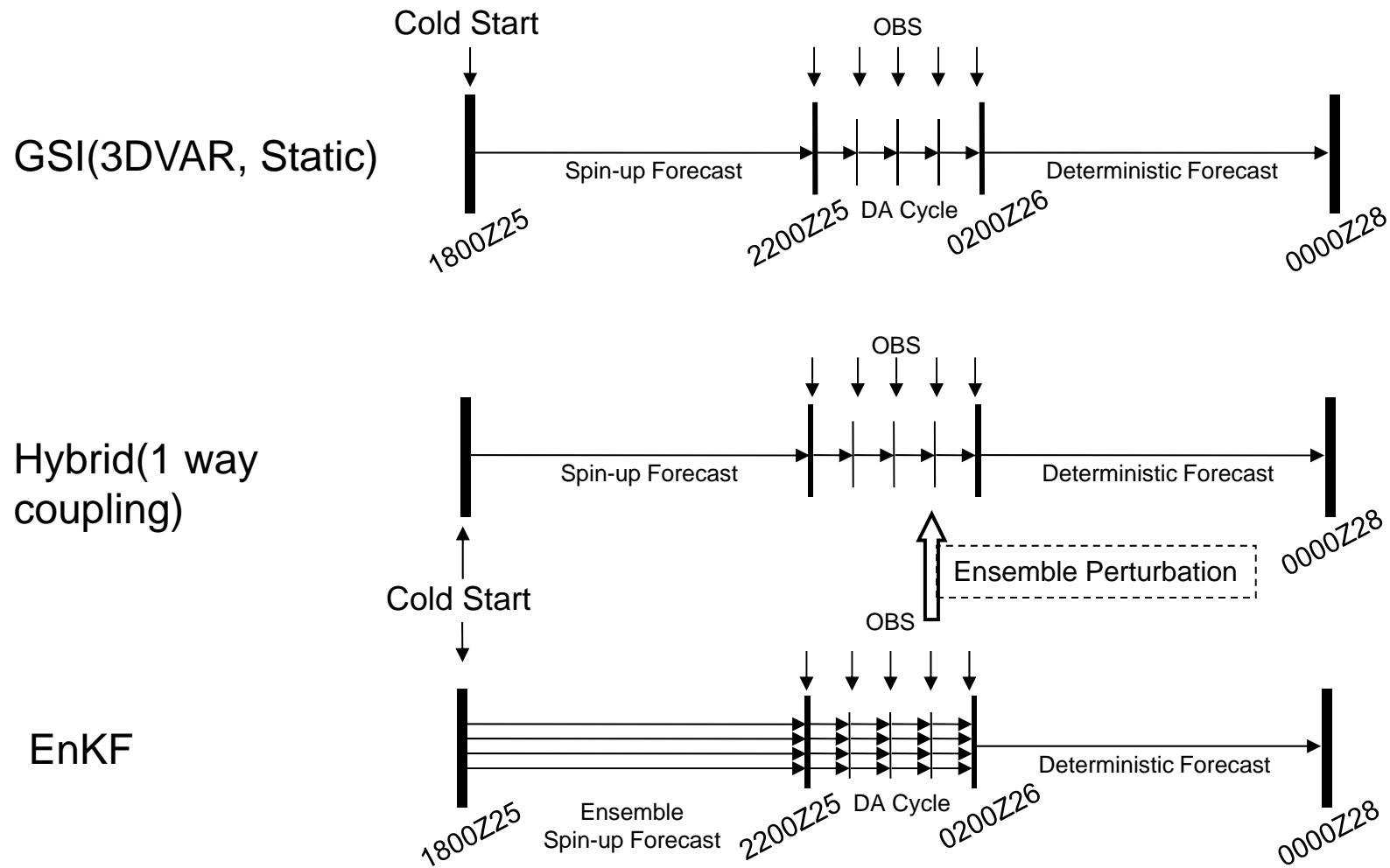


Evolution during TDR missions





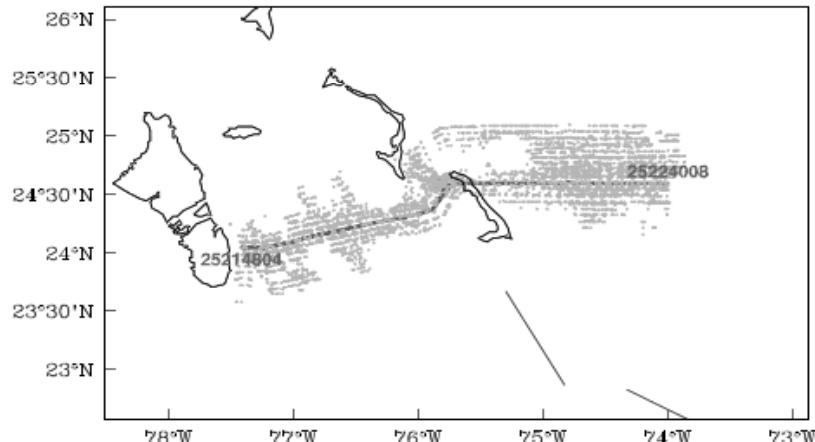
DA cycling configuration (mission 1)



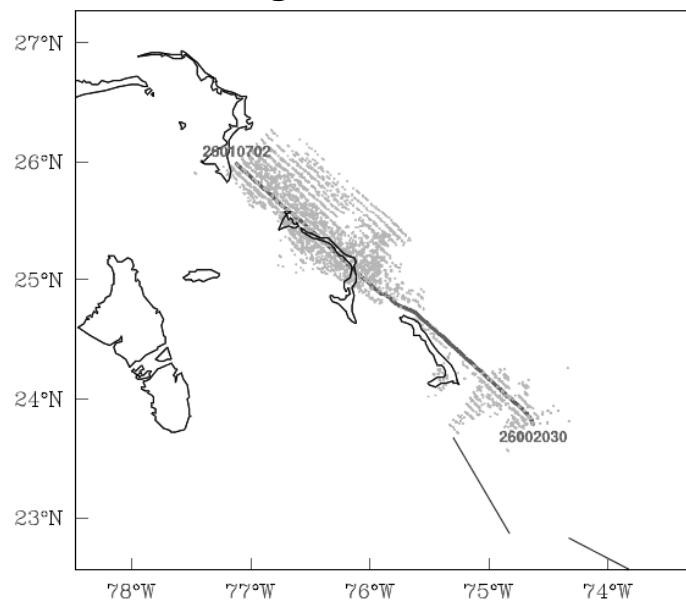


TDR data distribution (mission 1)

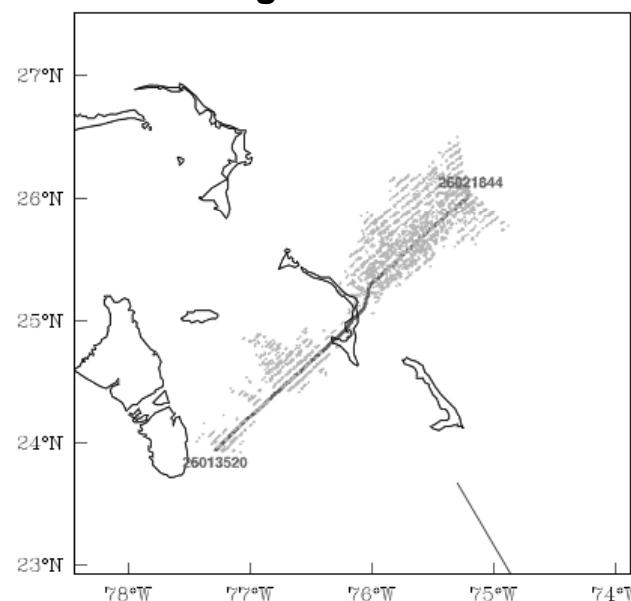
Vr & flight track 2200Z25



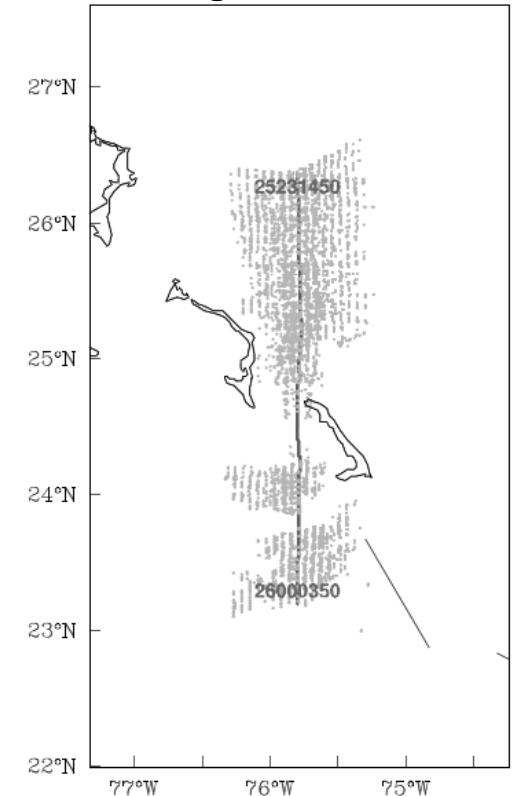
Vr & flight track 0030Z26



Vr & flight track 0200Z26

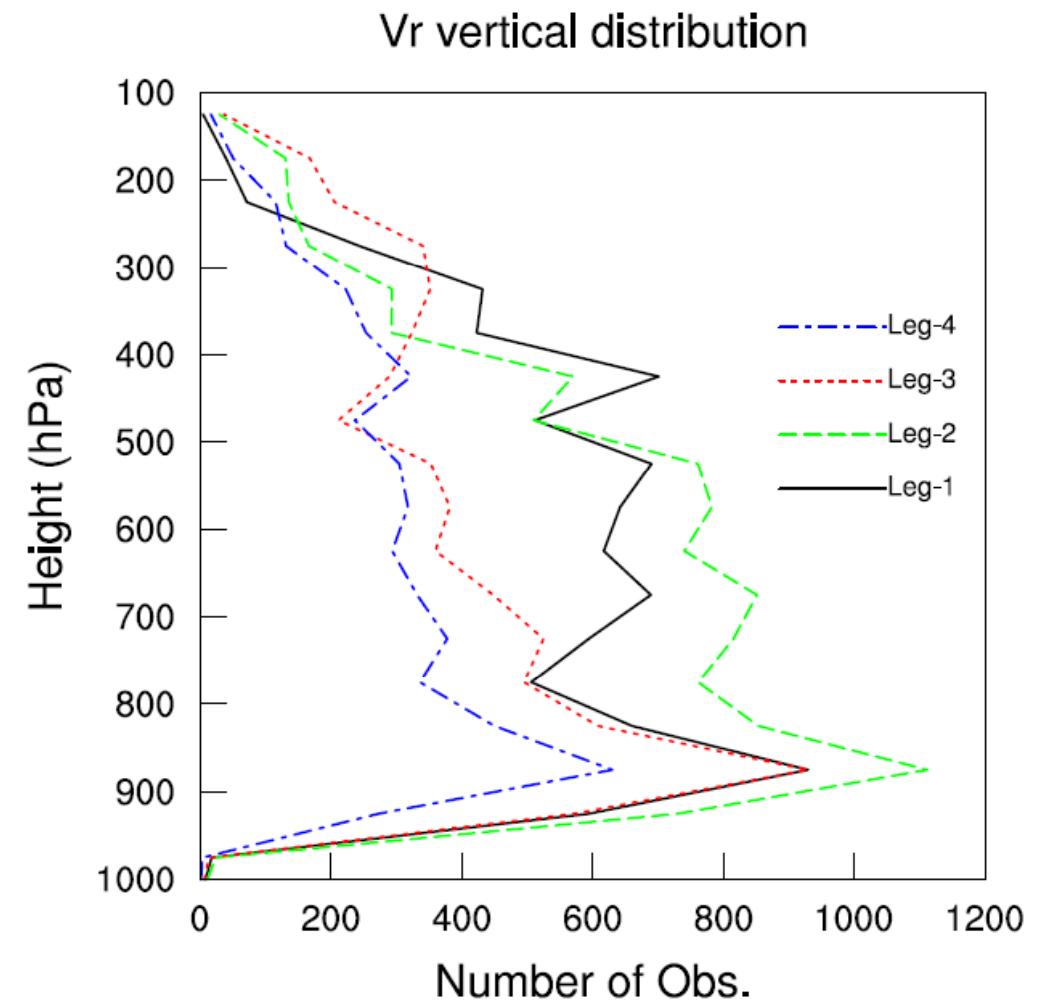
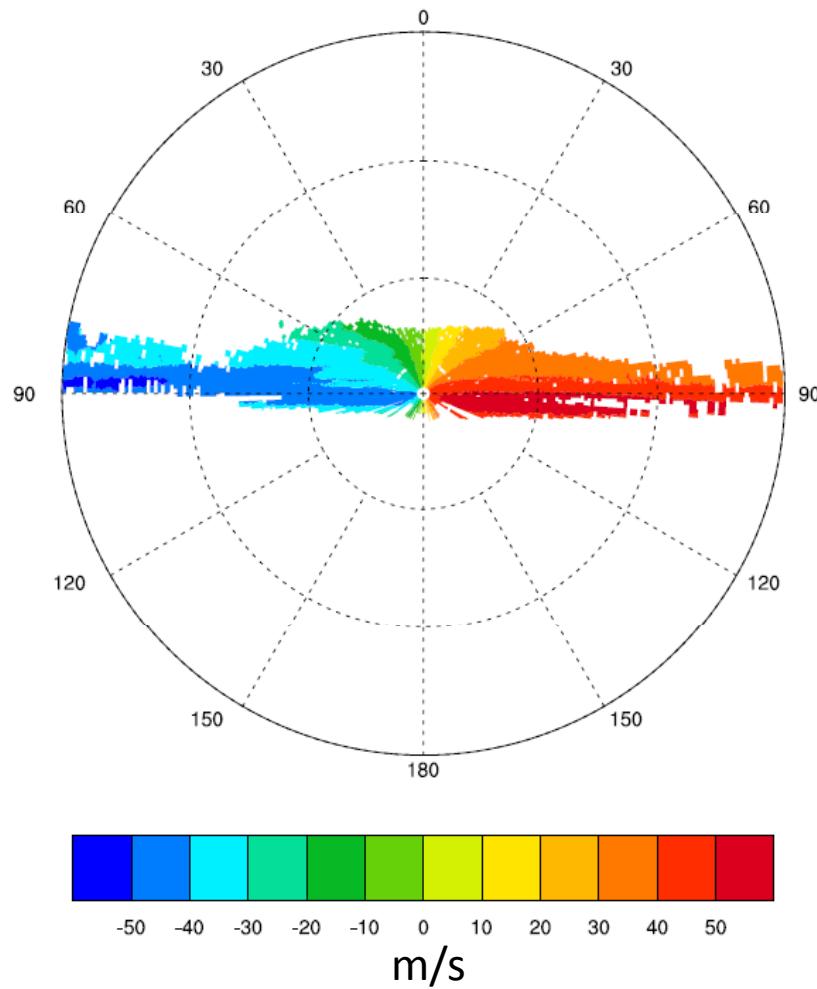


Vr & flight track 2330Z25





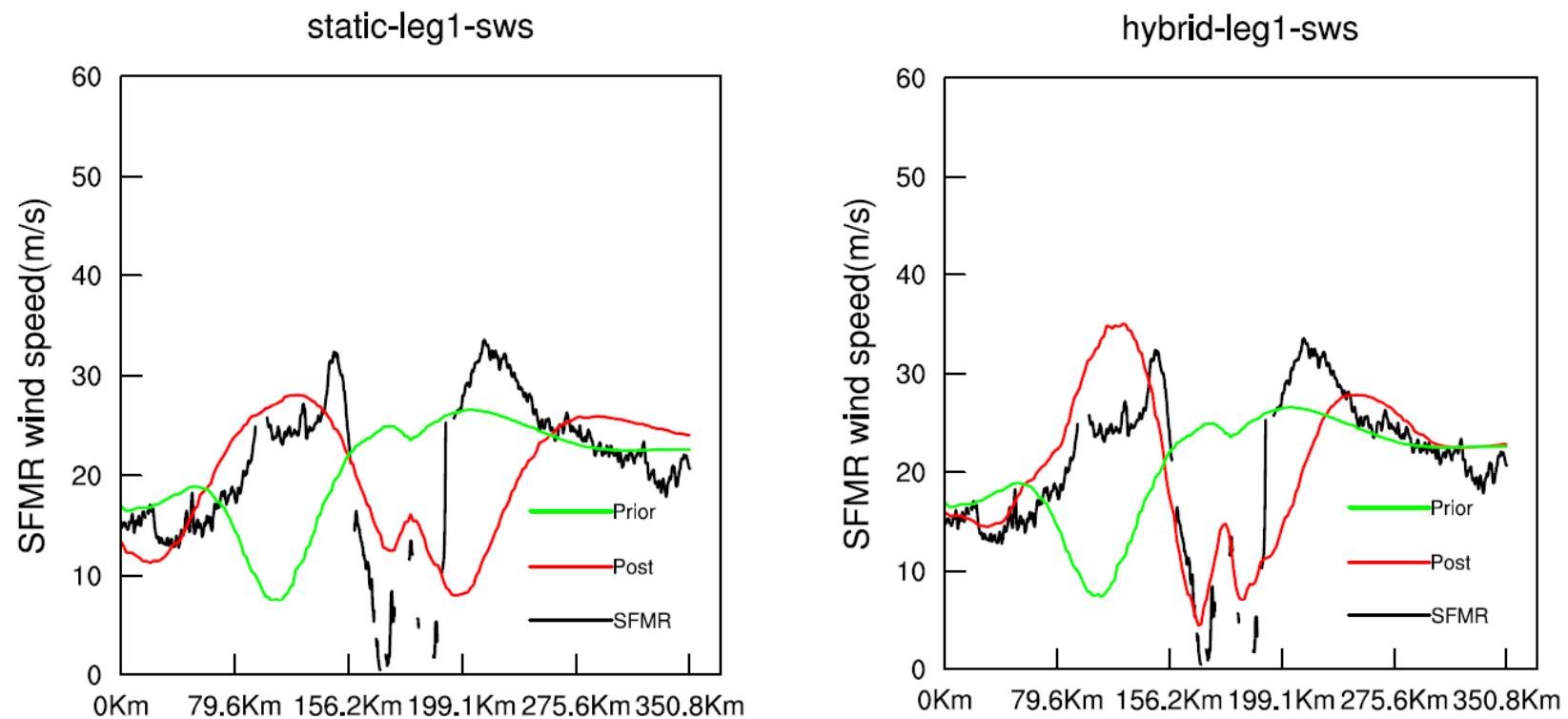
TDR data distribution (mission 1)





Verification against SFMR wind speed

First Leg

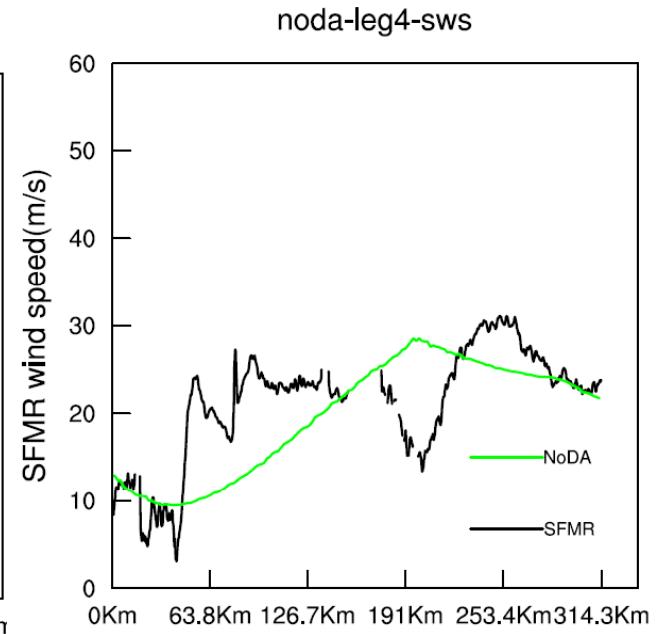
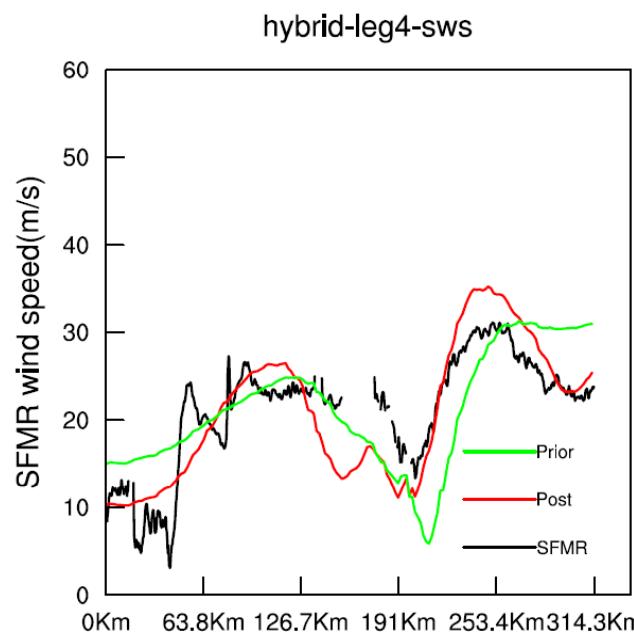
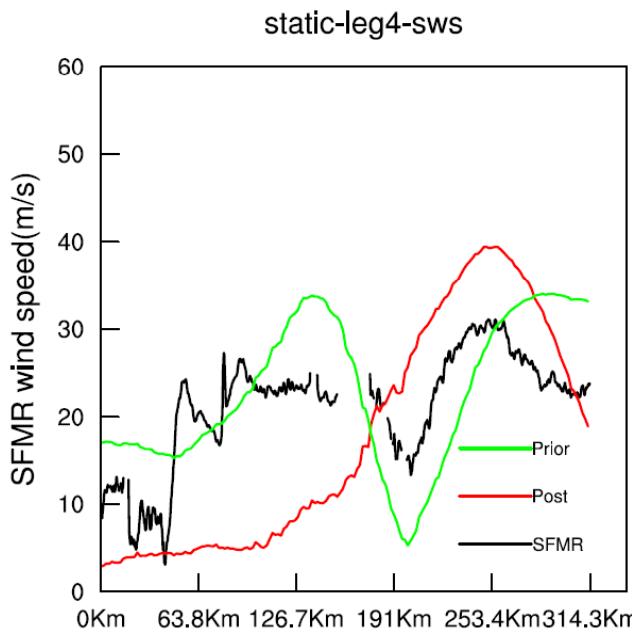


Acknowledge HRD to make SFMR, flight level data available



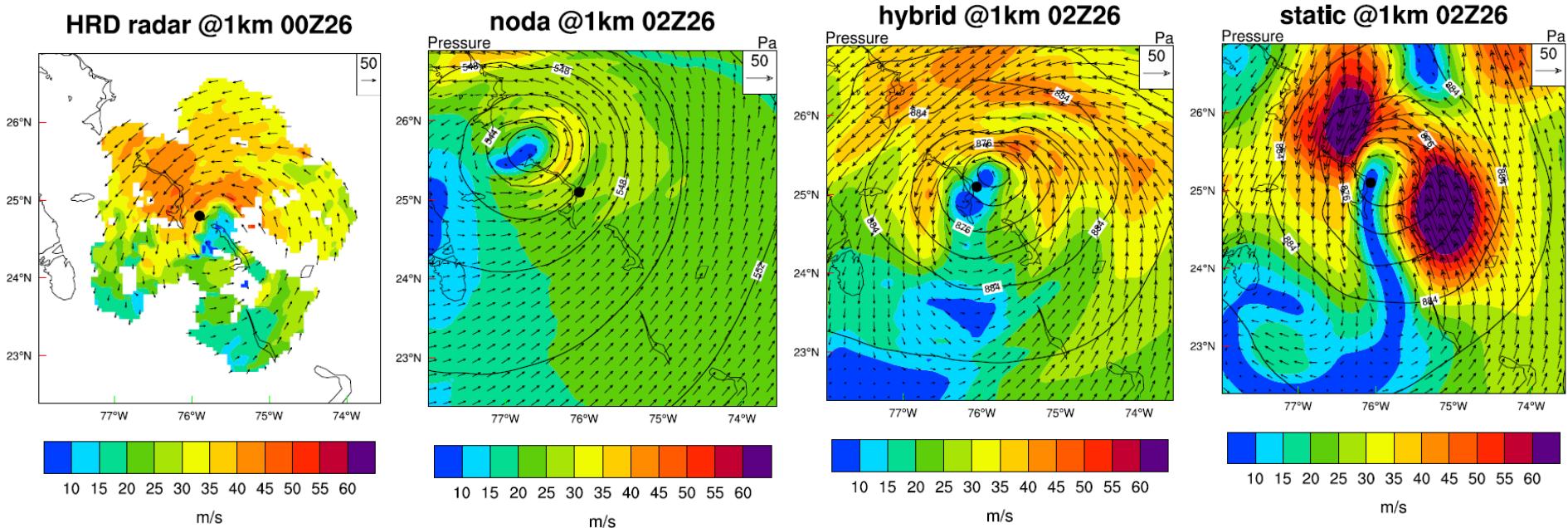
Verification against SFMR wind speed

Last Leg



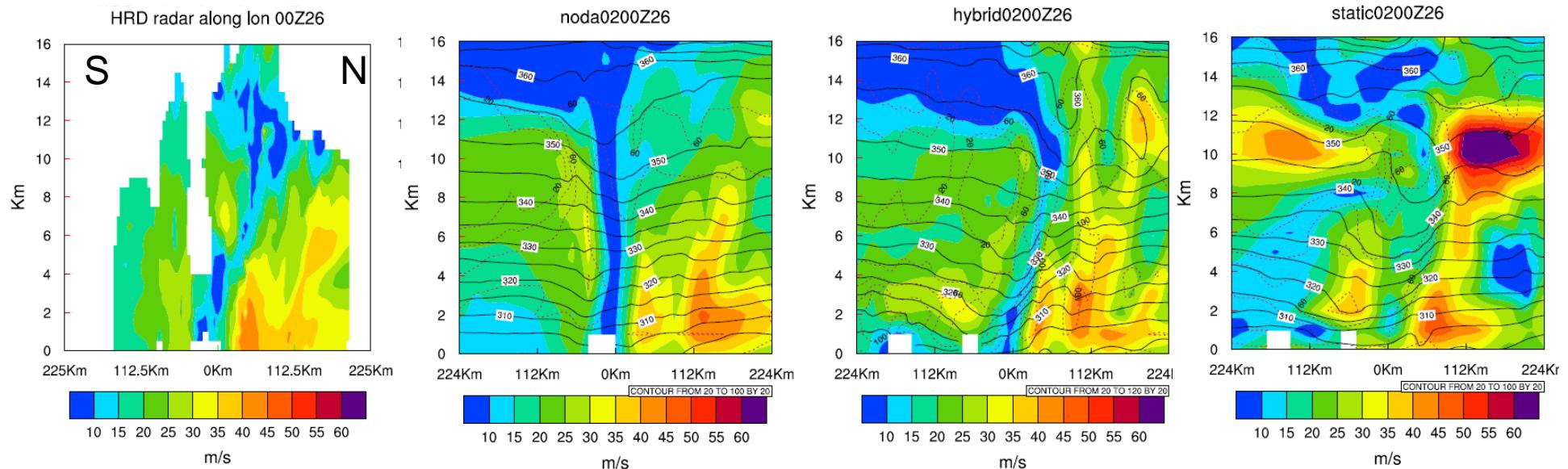


Comparison with HRD radar wind analysis



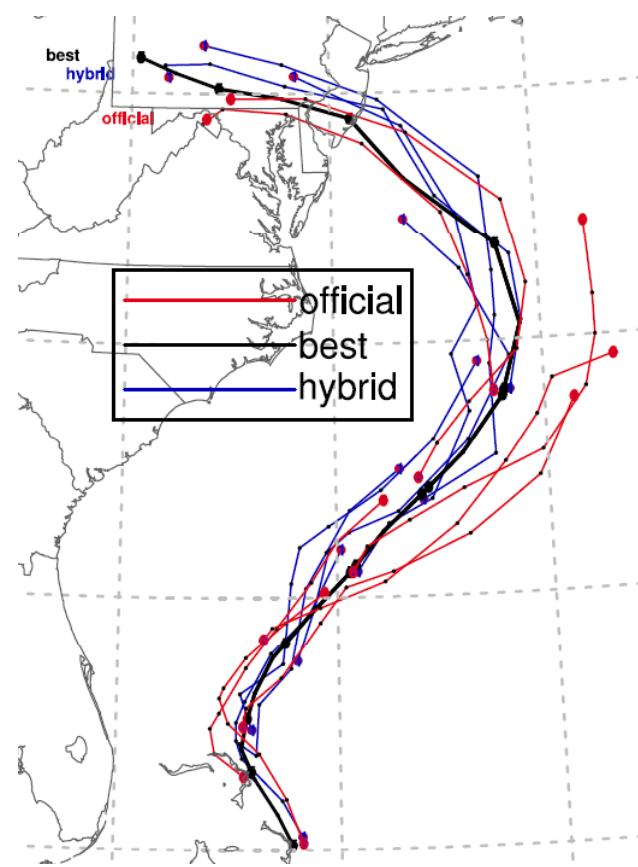
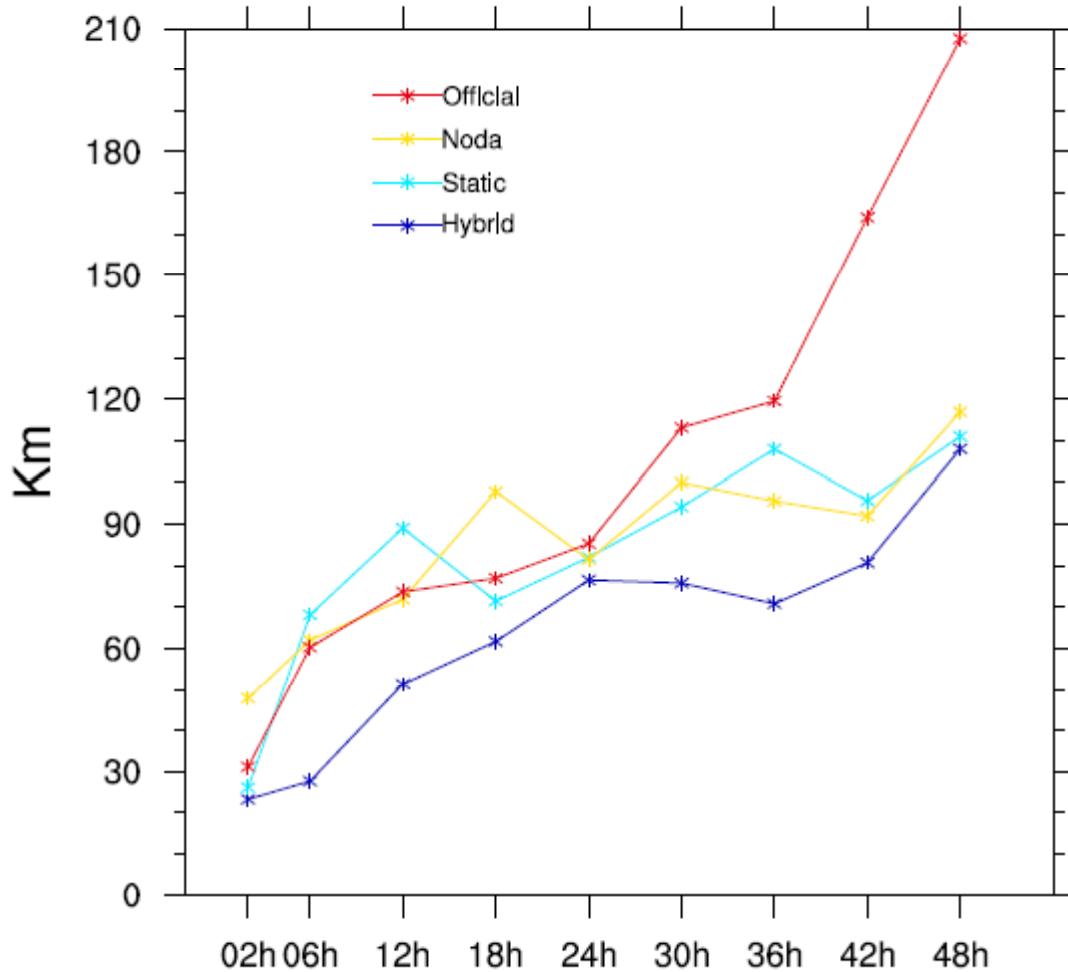


Comparison with radar wind analysis



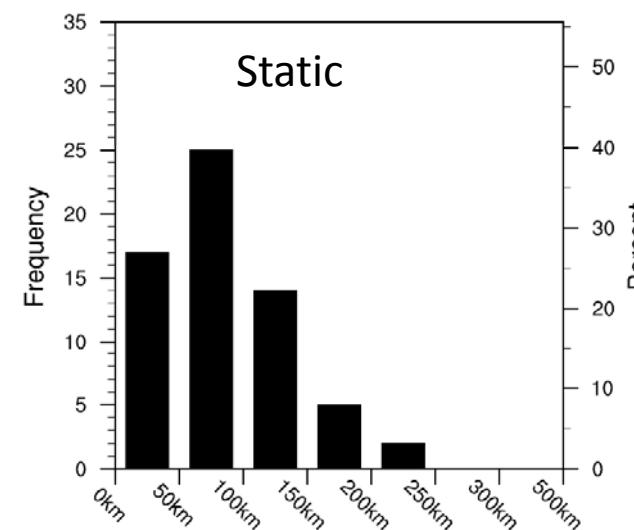
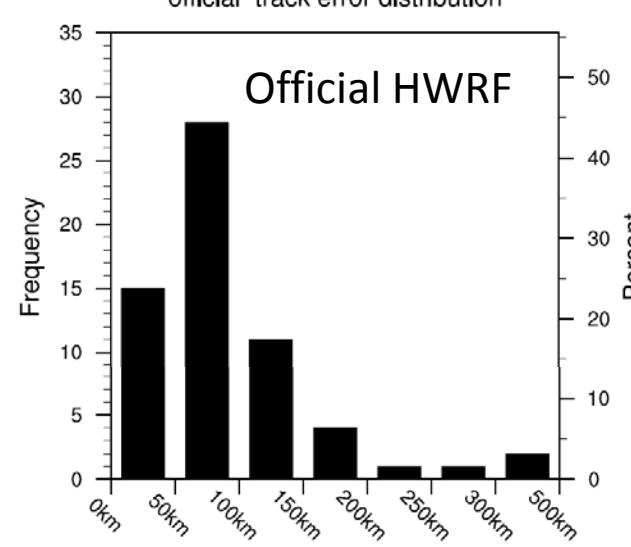
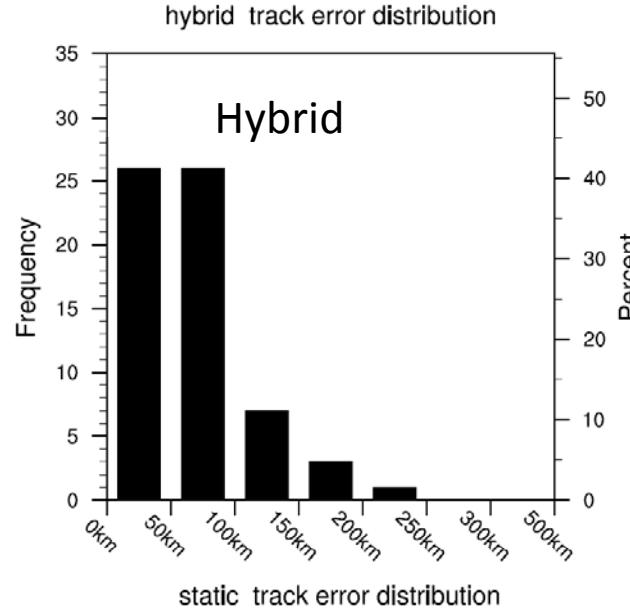
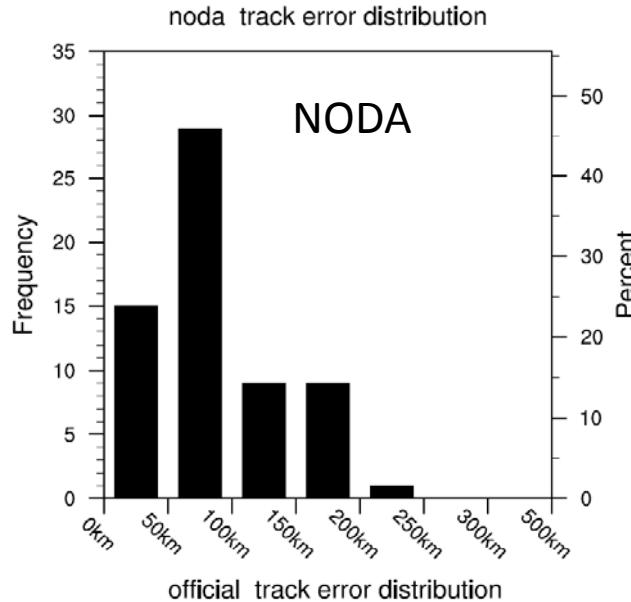


Track forecast (RMSE for 7 missions)



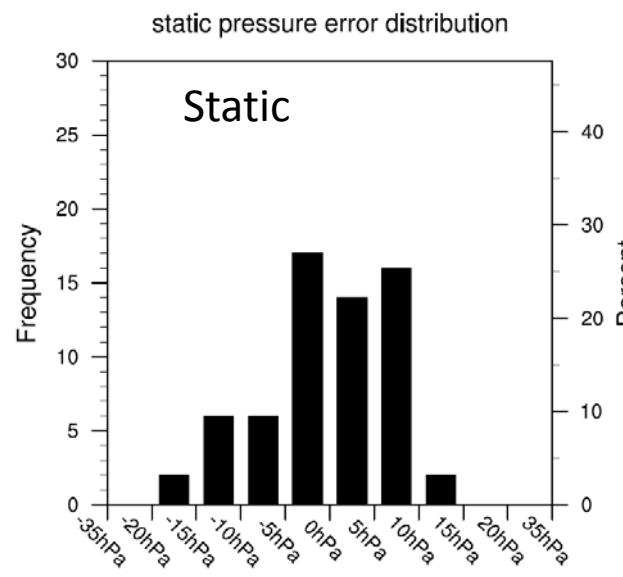
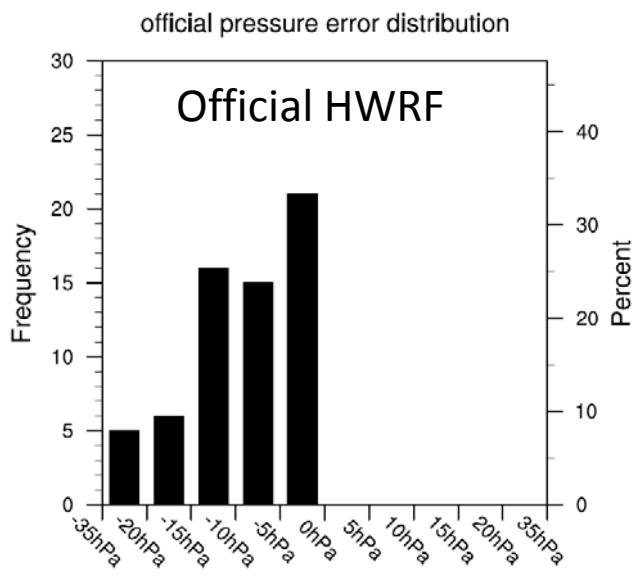
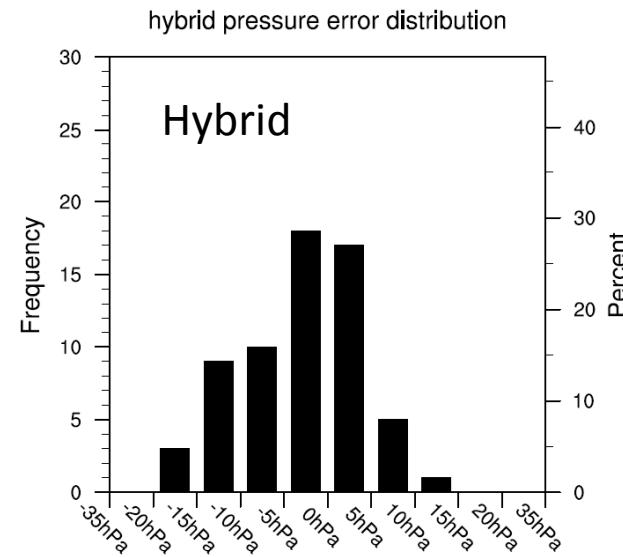
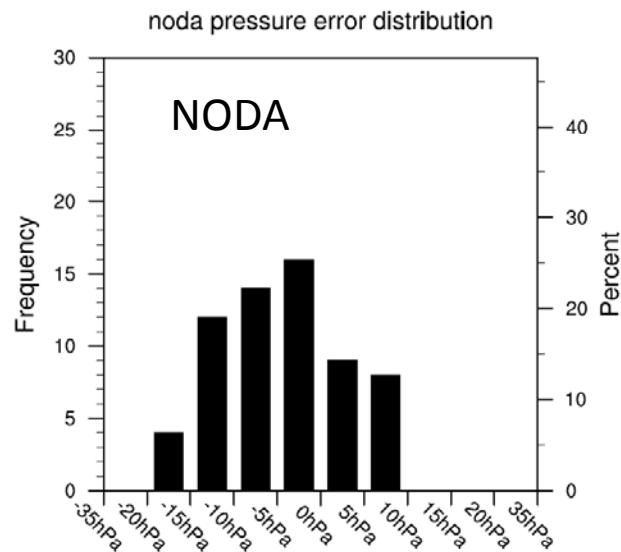


Track forecast (error distribution)



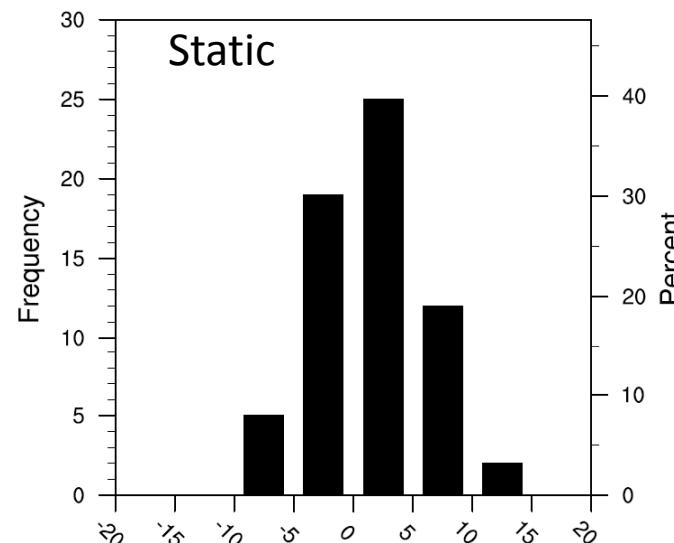
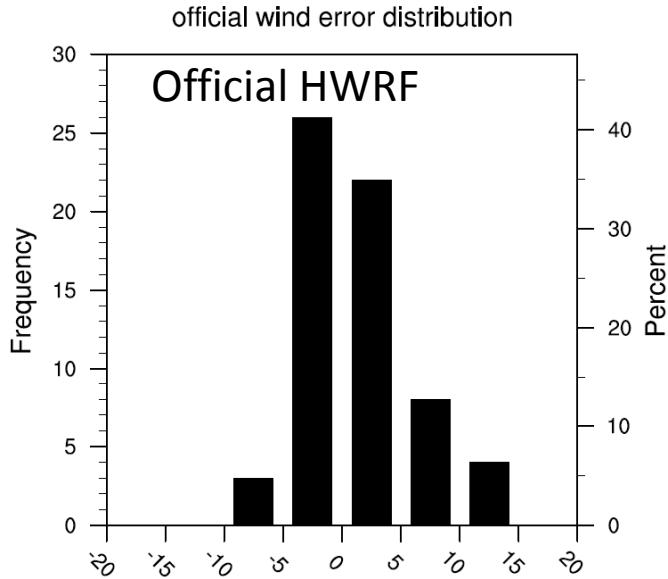
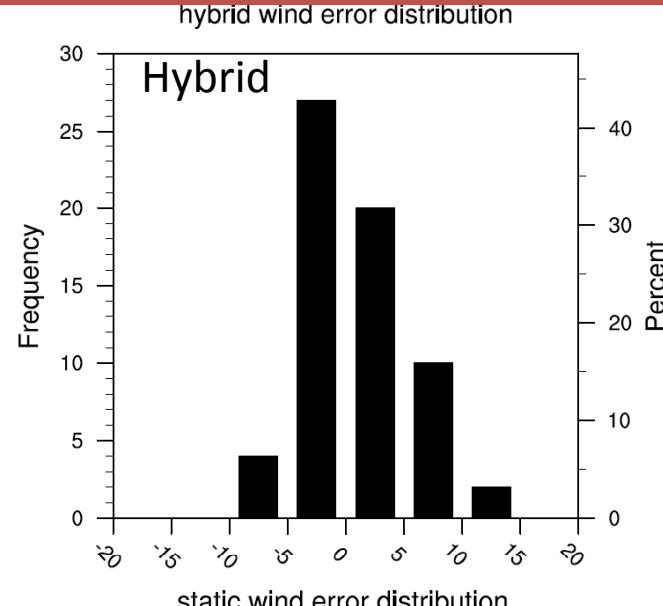
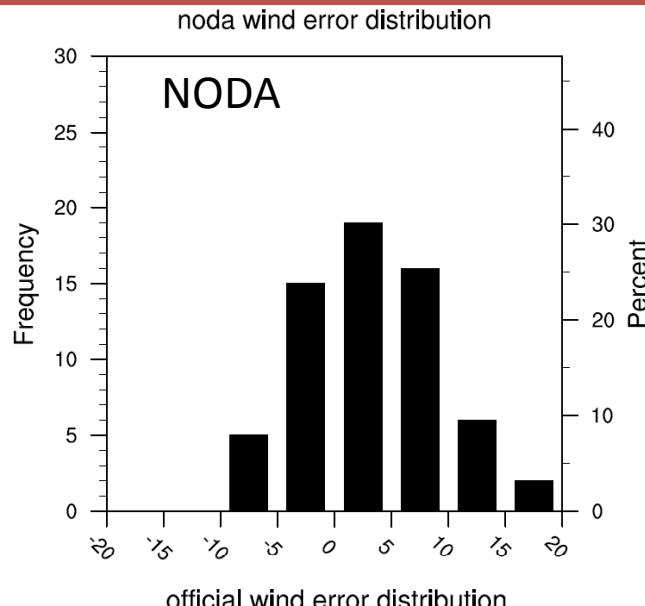


MSLP forecast (error distribution)



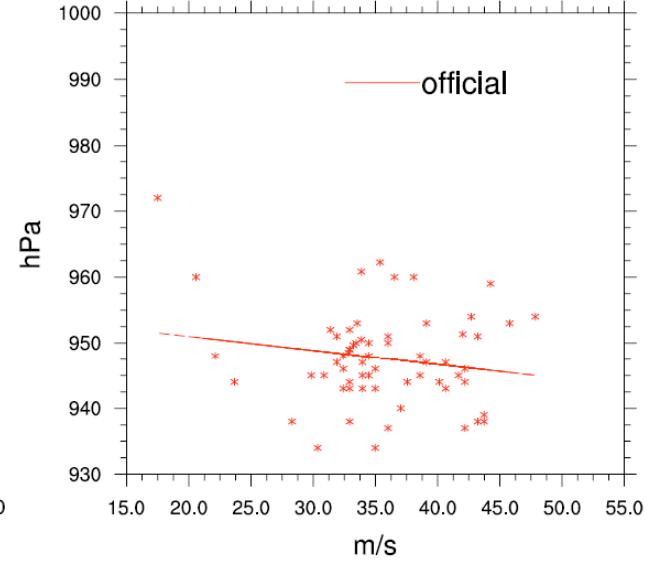
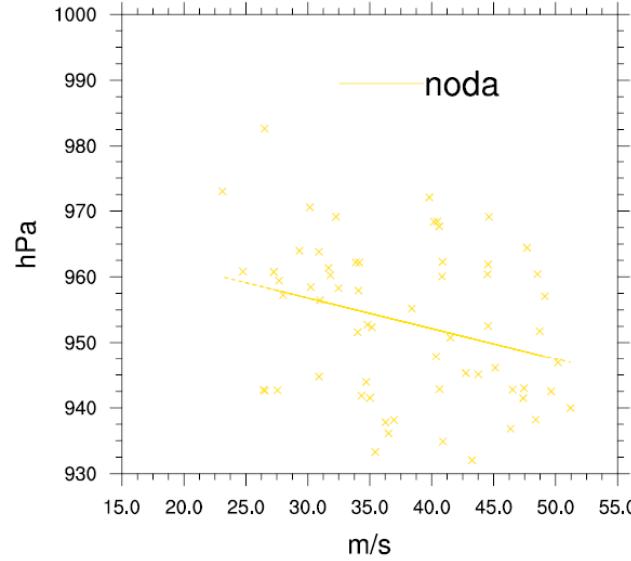
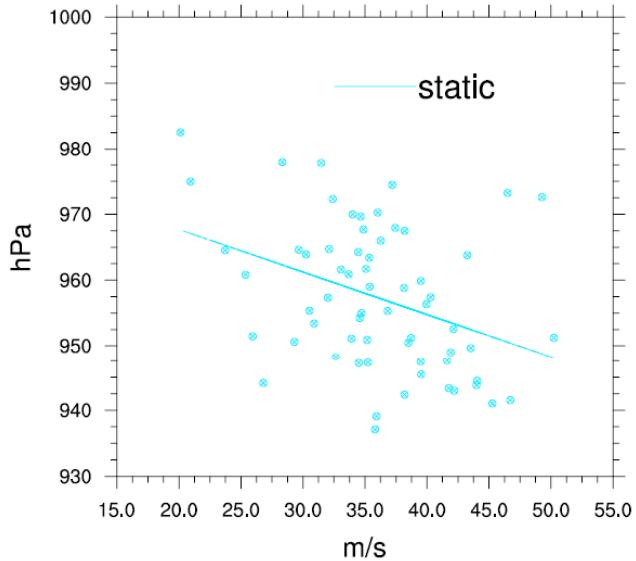
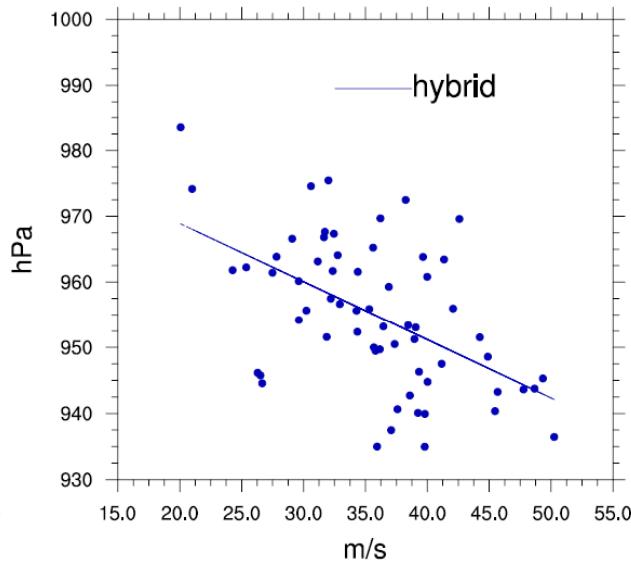
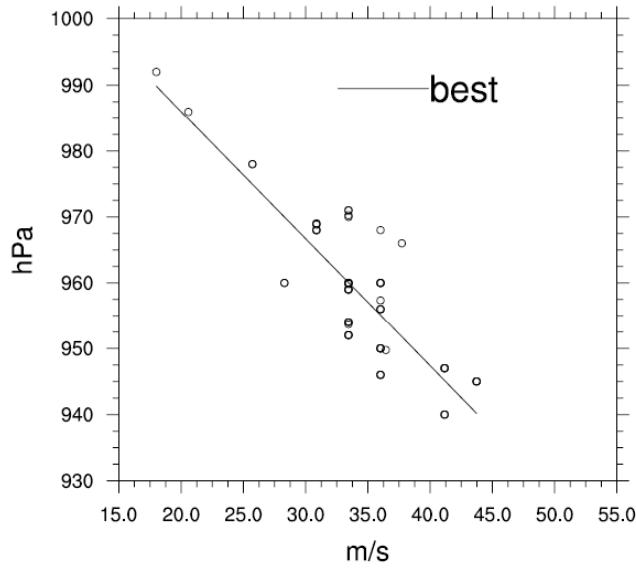


Max wind forecast (error distribution)



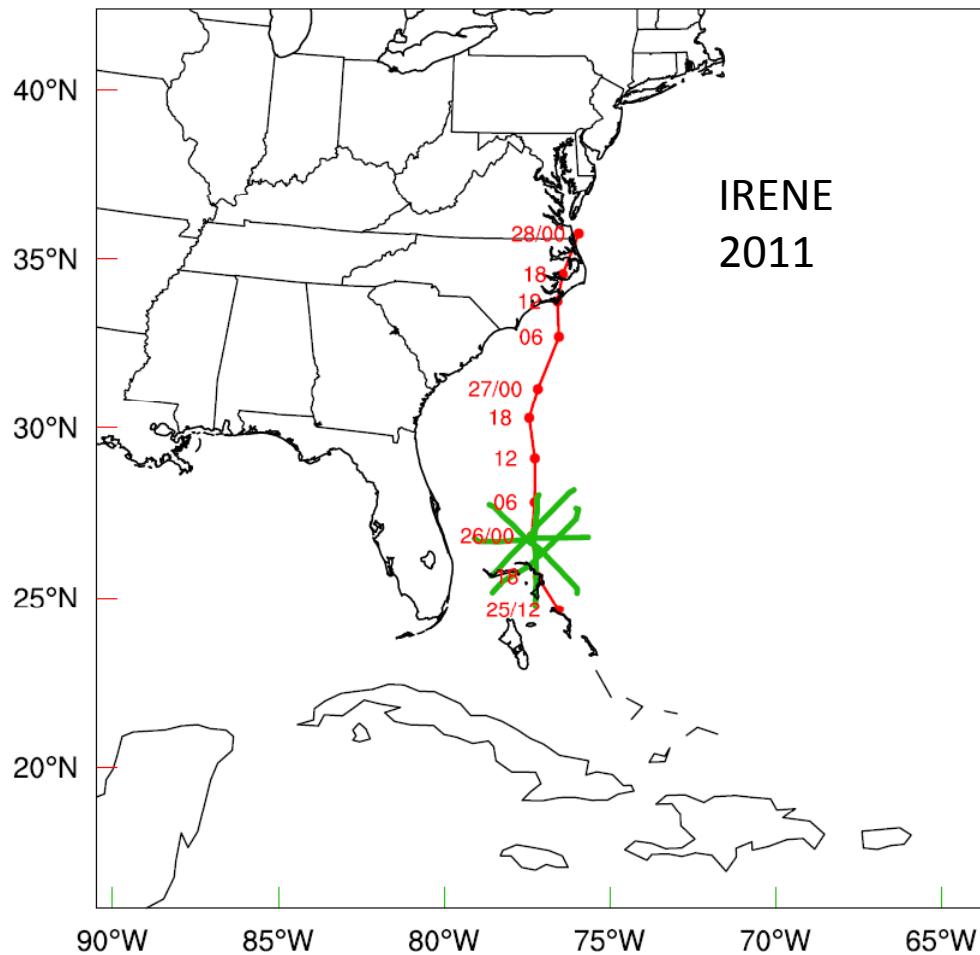


Max wind and MSLP relationship





Test with IRENE 2011



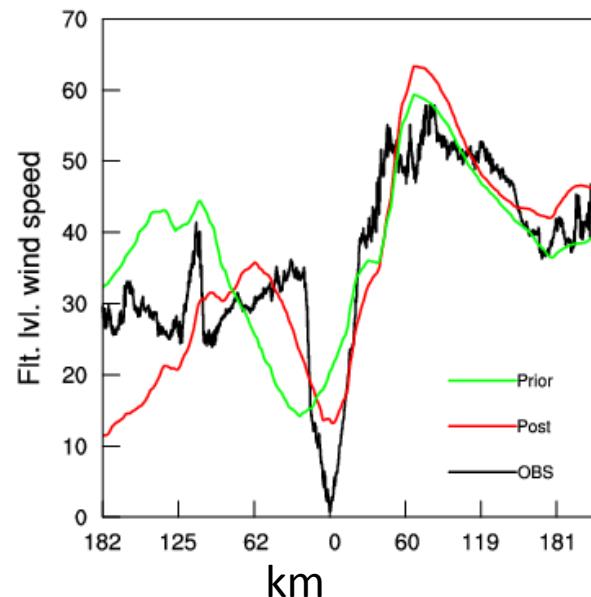
- Model: HWRF
- Observations: radial velocity from Tail Doppler Radar (TDR)
- Initial and LBC ensemble: GFS global hybrid DA system
- Ensemble size: 40



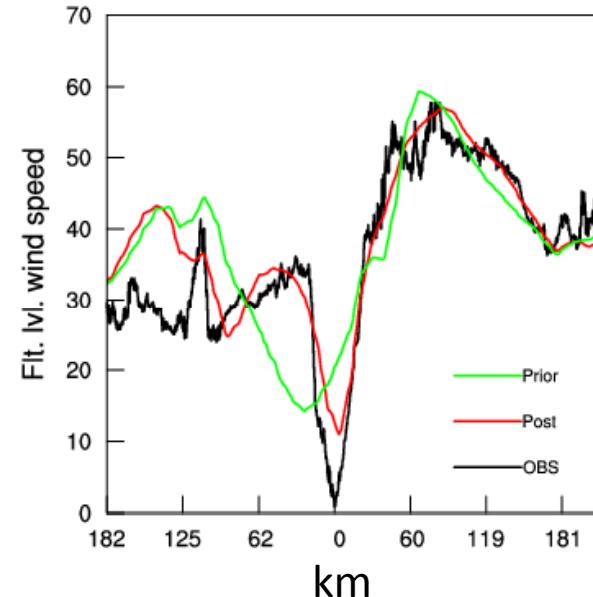
Verification against independent flight level wind speed

First Leg

Static



hybrid

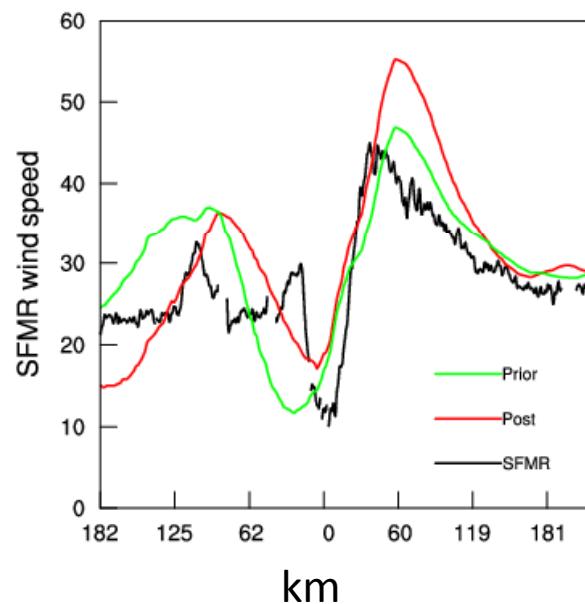




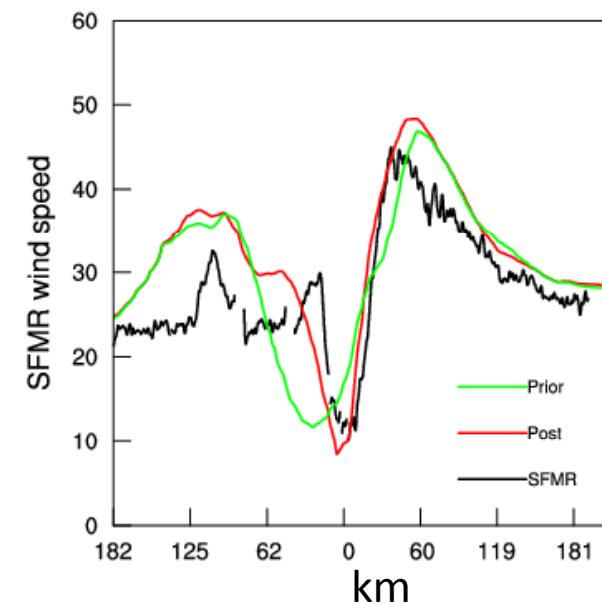
Verification against SFMR wind speed

First Leg

Static



hybrid

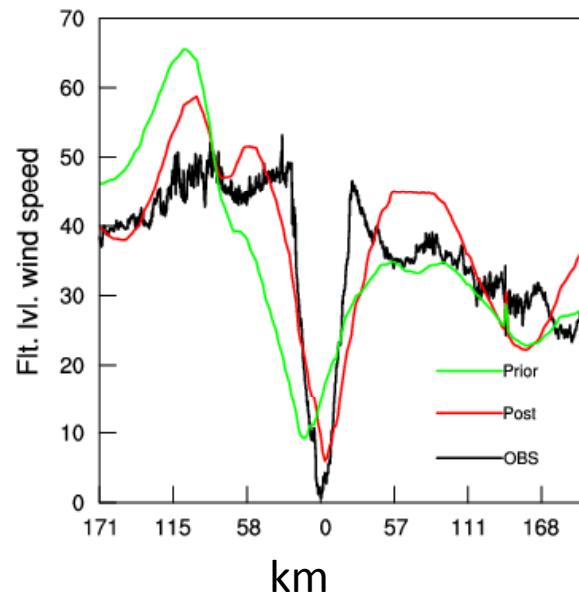




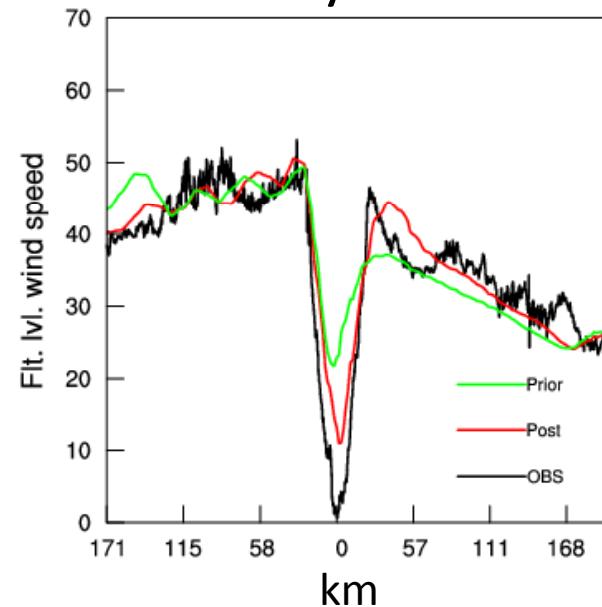
Verification against independent flight level wind speed

Last Leg

static



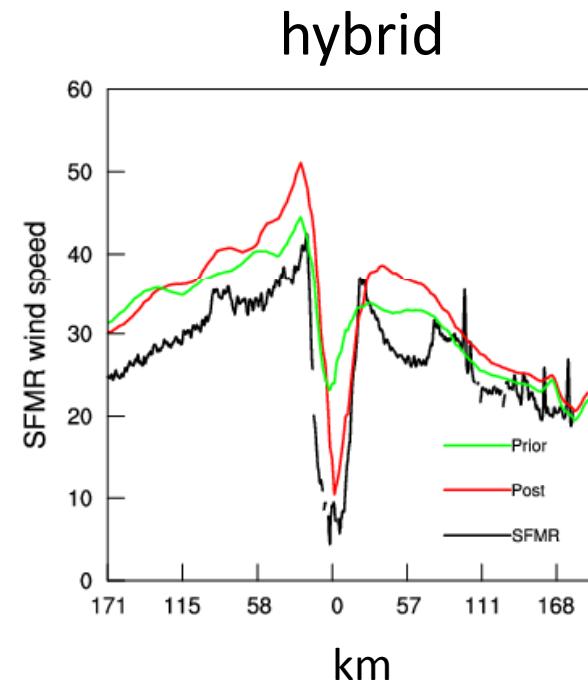
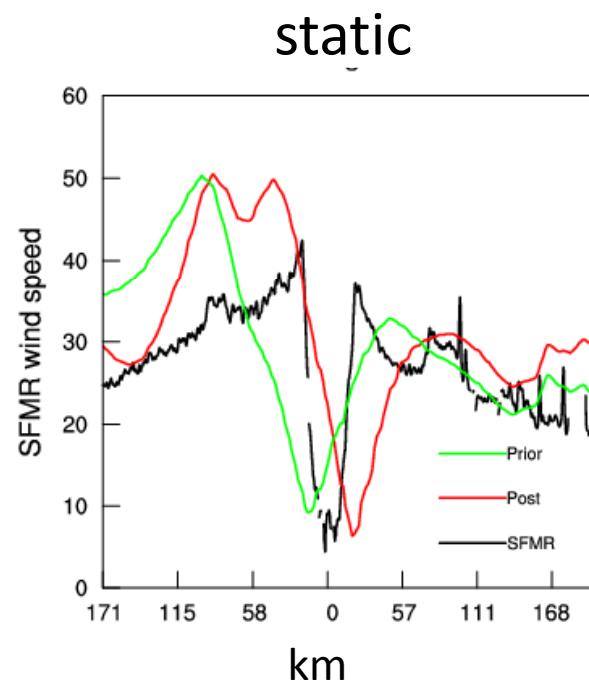
hybrid





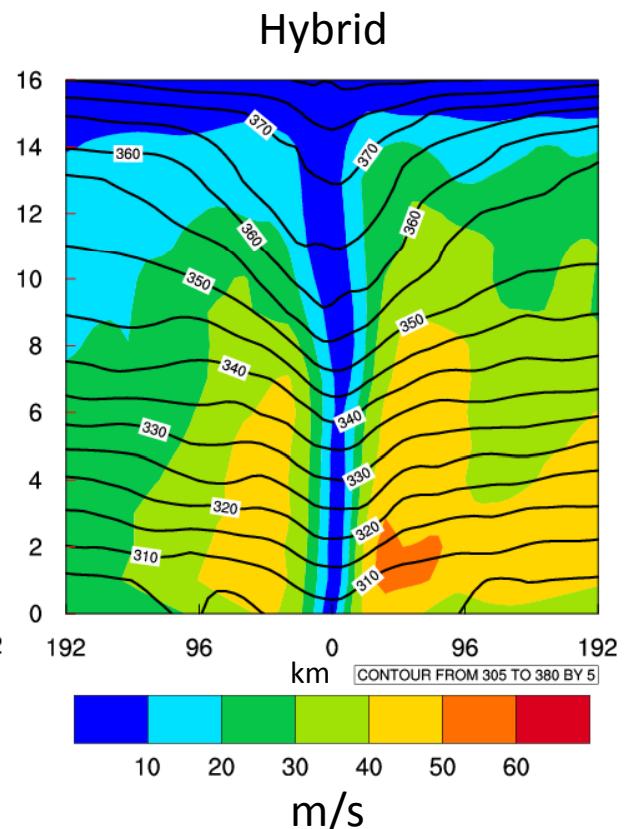
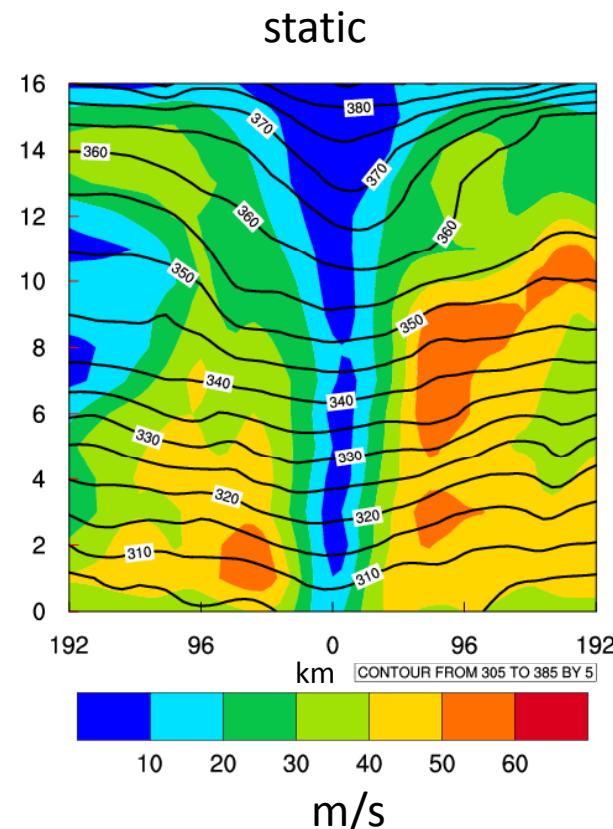
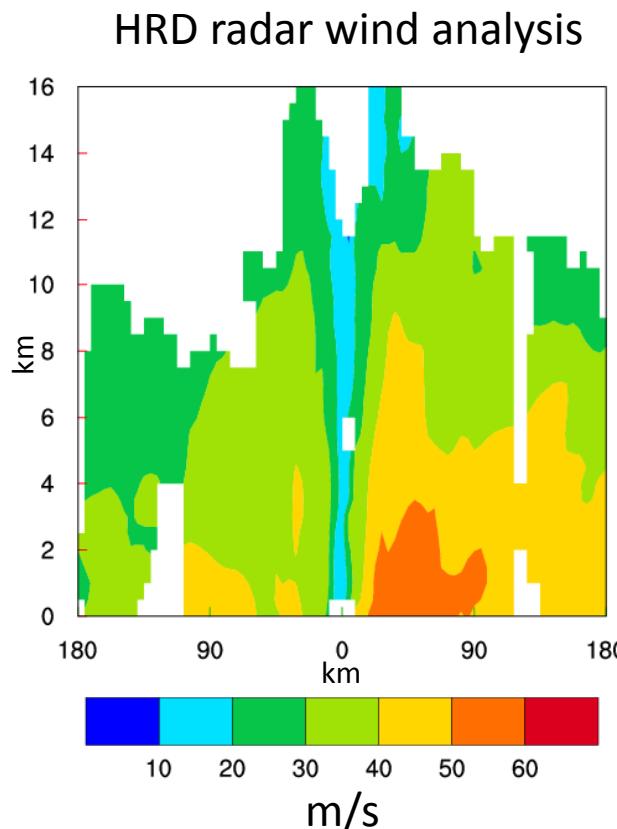
Verification against SFMR wind speed

Last Leg





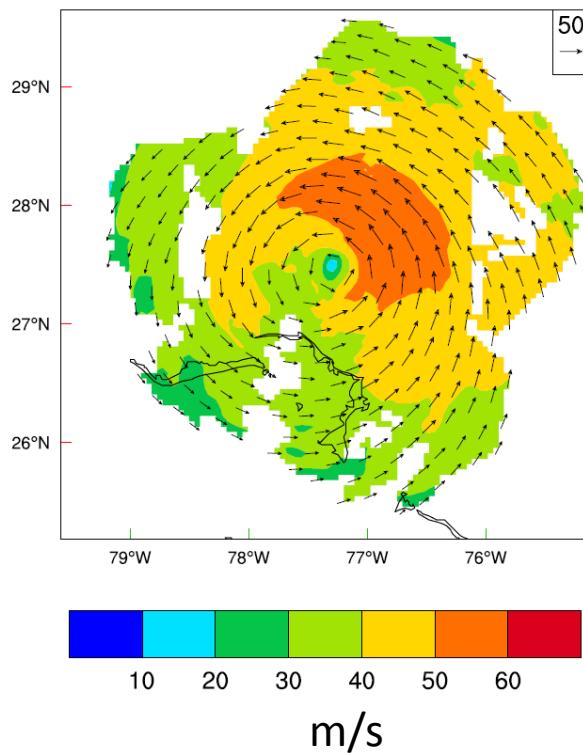
Comparison with HRD radar wind analysis



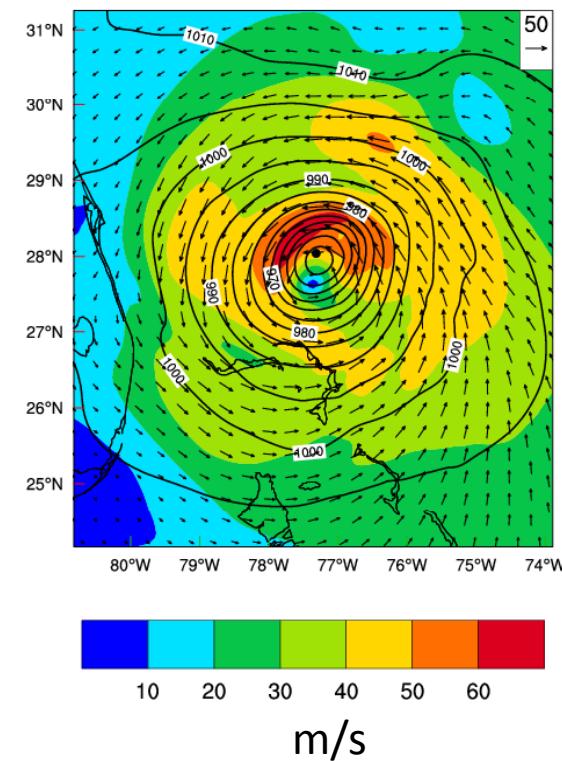


Comparison with radar wind analysis

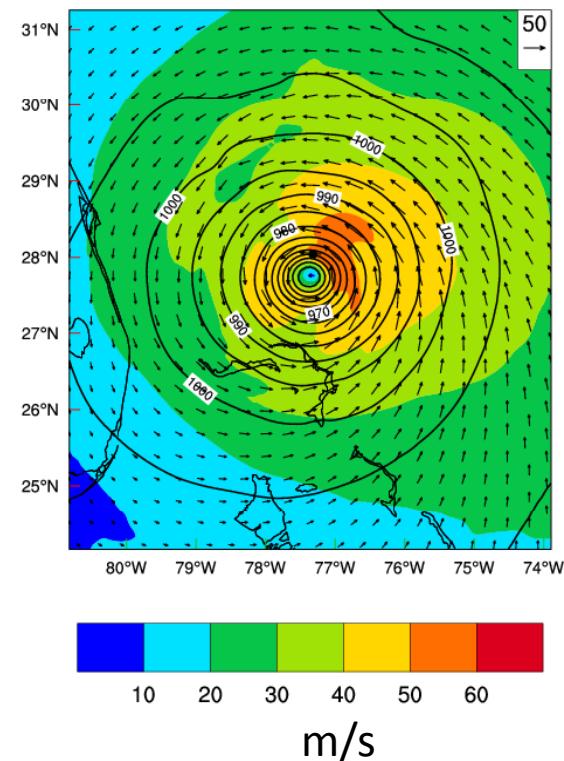
HRD radar wind analysis @ 1km



static @ 1km



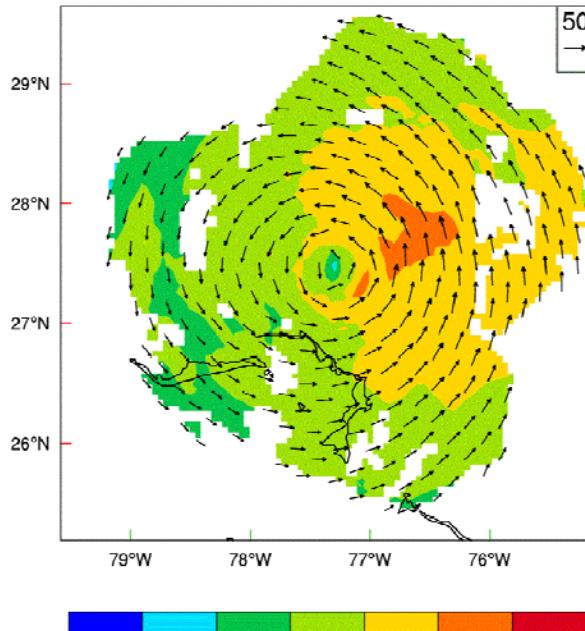
Hybrid @ 1km





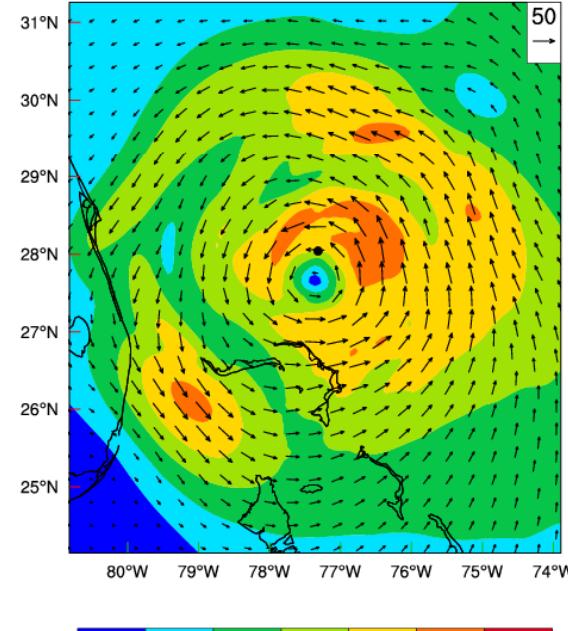
Comparison with radar wind analysis

HRD radar wind analysis @ 3km



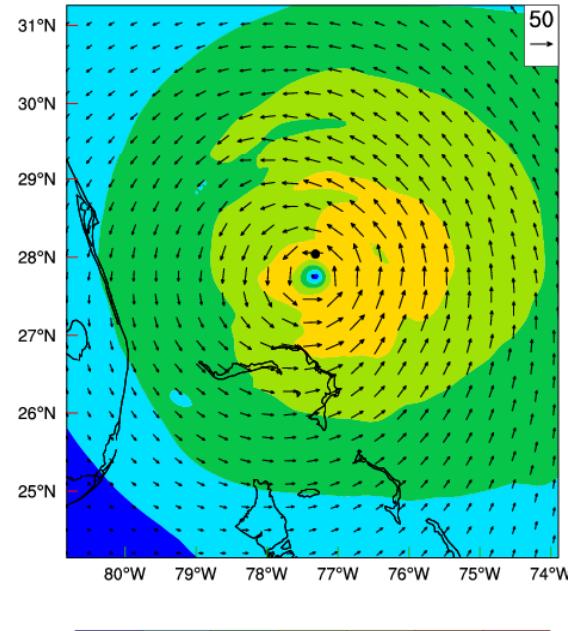
m/s

static @ 3km



m/s

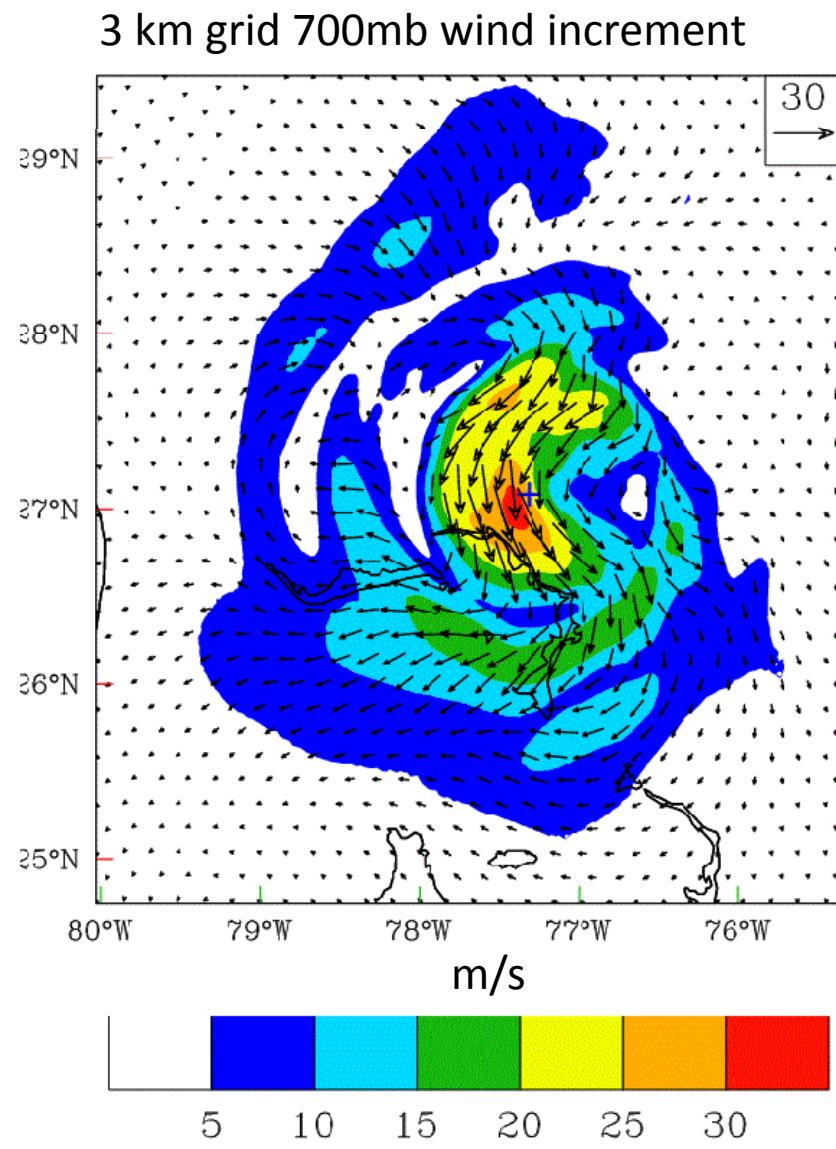
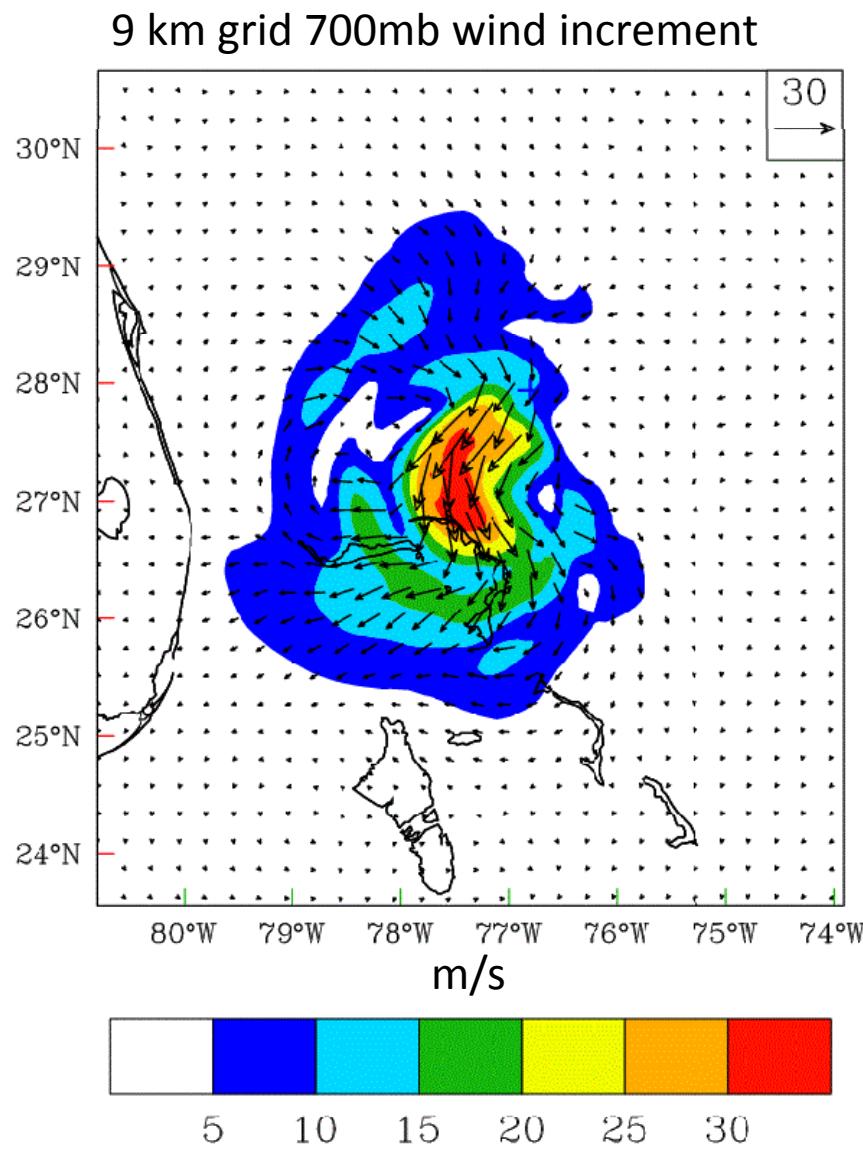
Hybrid @ 3km



m/s



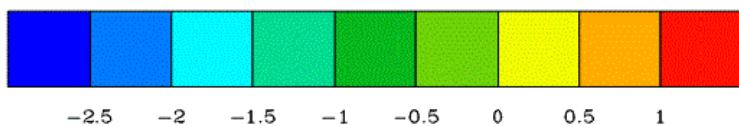
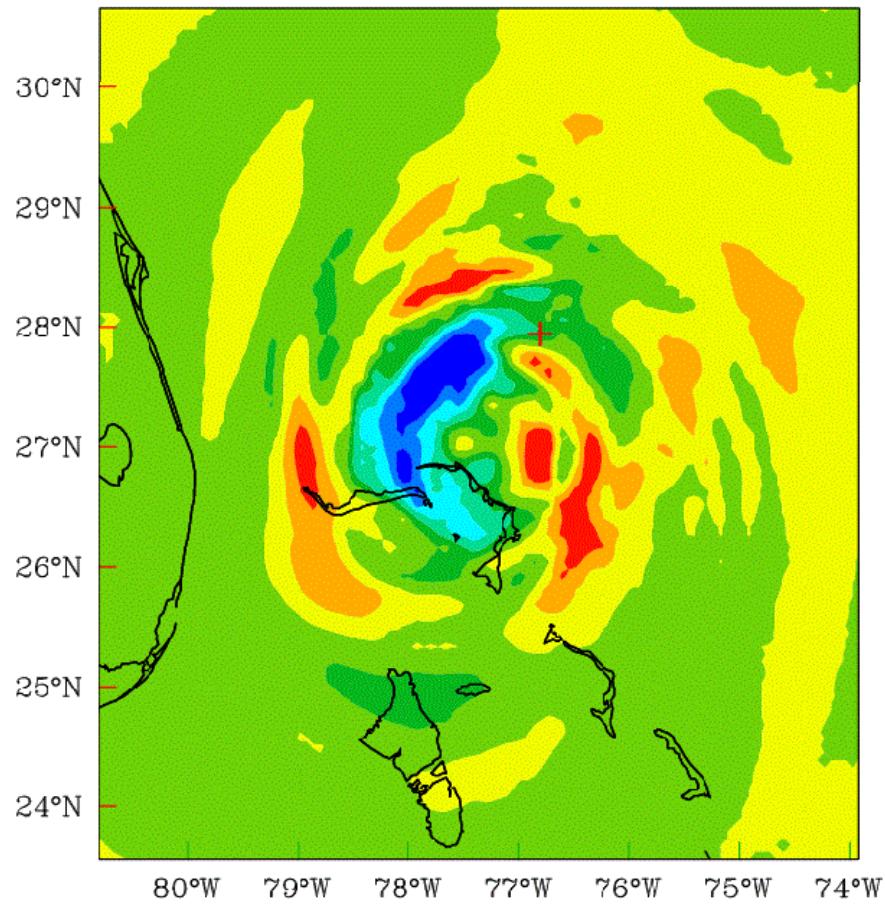
3km-9km dual resolution hybrid DA with moving nest



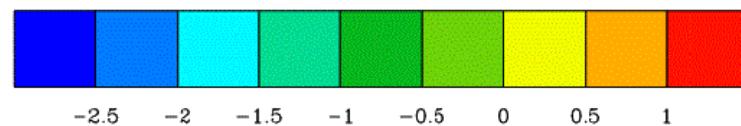
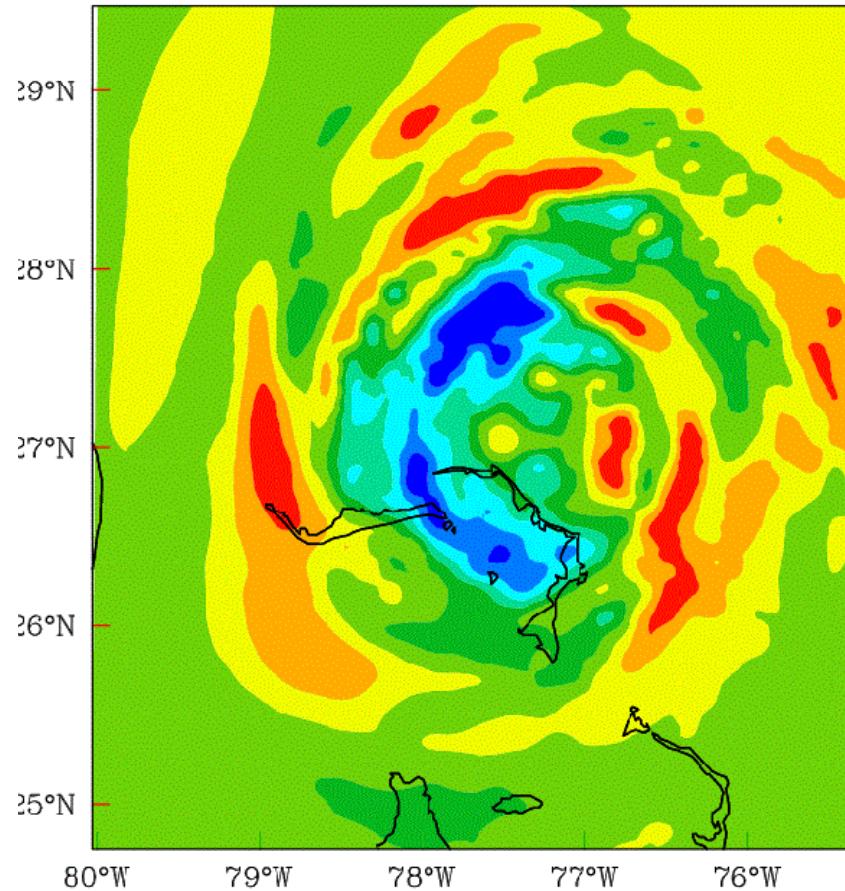


3km-9km dual resolution hybrid DA with moving nest

9 km grid 700mb temp increment



3 km grid 700mb temp increment



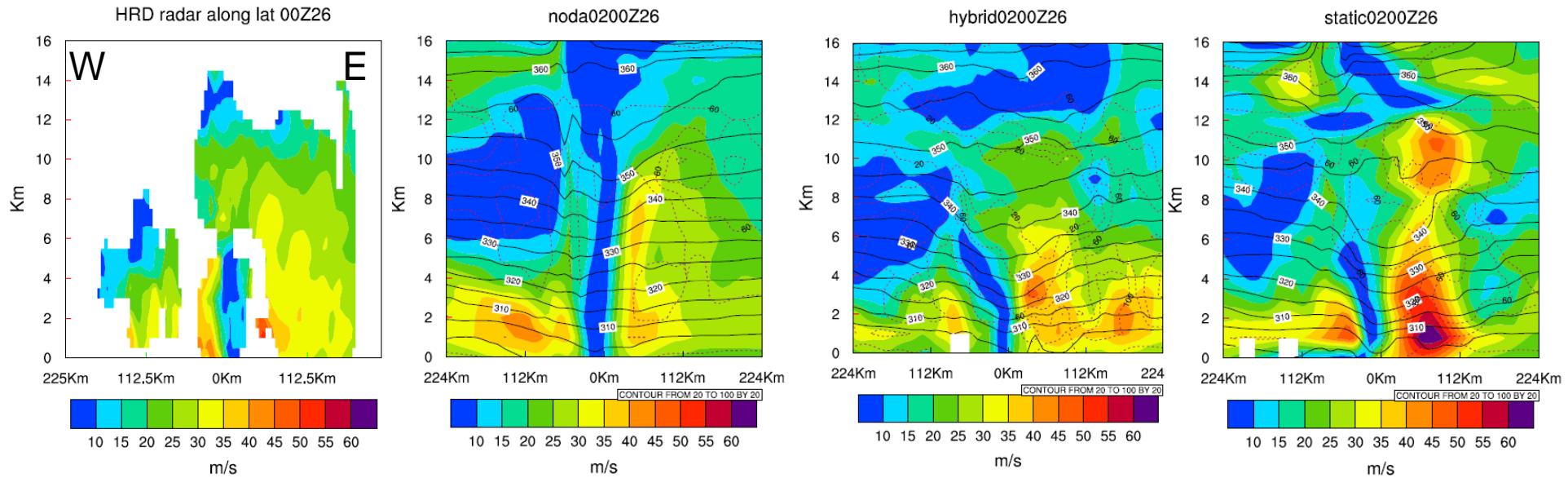


Summary and ongoing work

- a. The GSI-based hybrid EnKF-Var data assimilation system including both the Var and EnKF components were expanded to HWRF.
- b. TDR data assimilation capability was added/enhanced for the HWRF hybrid DA.
- c. Some of the development/enhancement is transitioned in 2013 HWRF operational DA system.
- d. TDR data improved TC structure analysis and forecast, TC track and MSLP forecasts.
- e. Various diagnostics and verifications suggested incorporating ensemble in GSI hybrid provided more skillful TC analysis and forecasts than the GSI 3DVar.
- f. Testing more missions/cases.
- g. Develop and research on various new capabilities for HWRF hybrid (dual resolution hybrid, etc.).

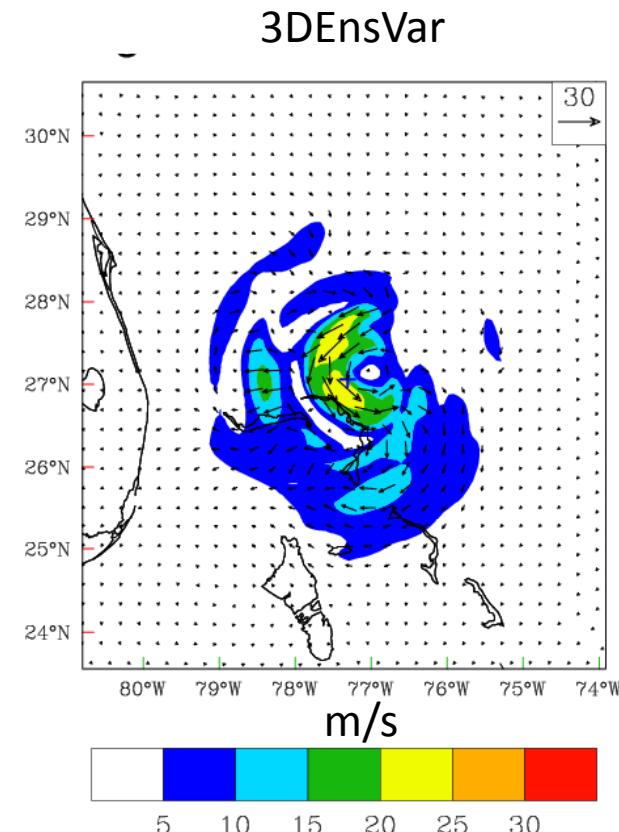
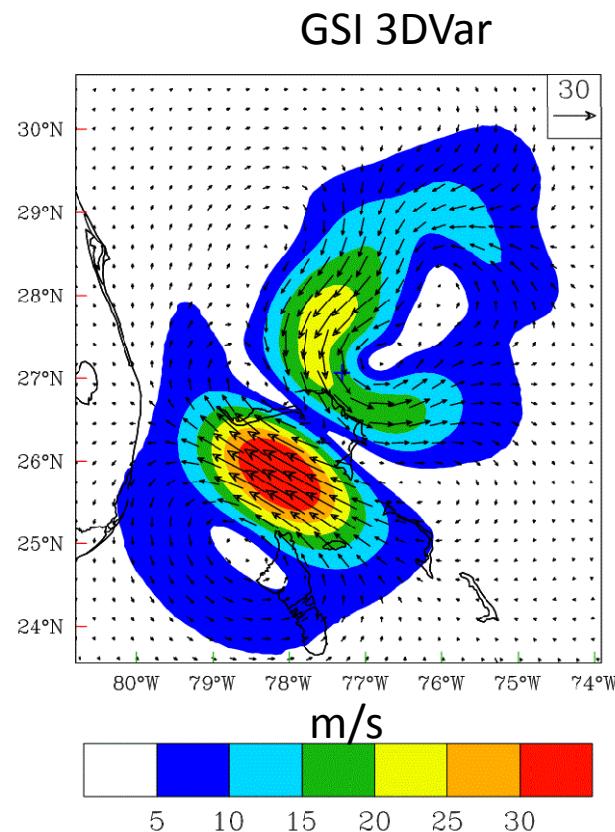


Comparison with radar wind analysis



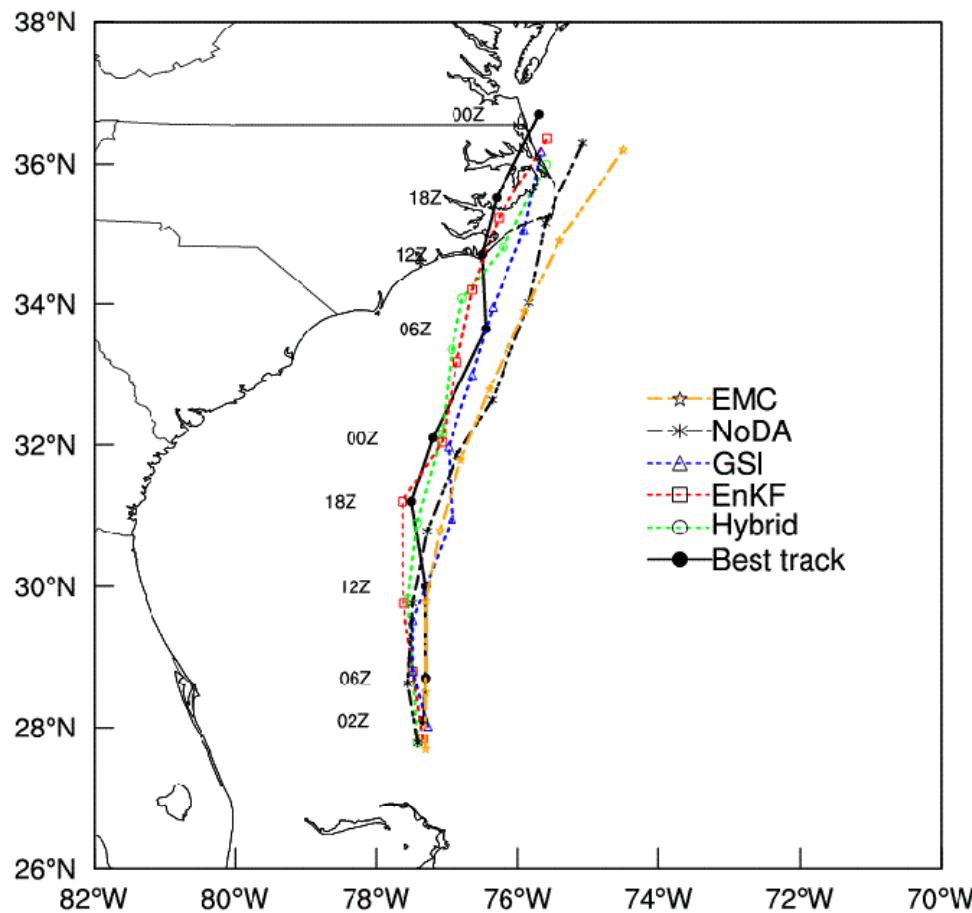


700 mb wind increment





Track forecast



EMC: HWRF official forecast

NoDA: no TDR assimilation

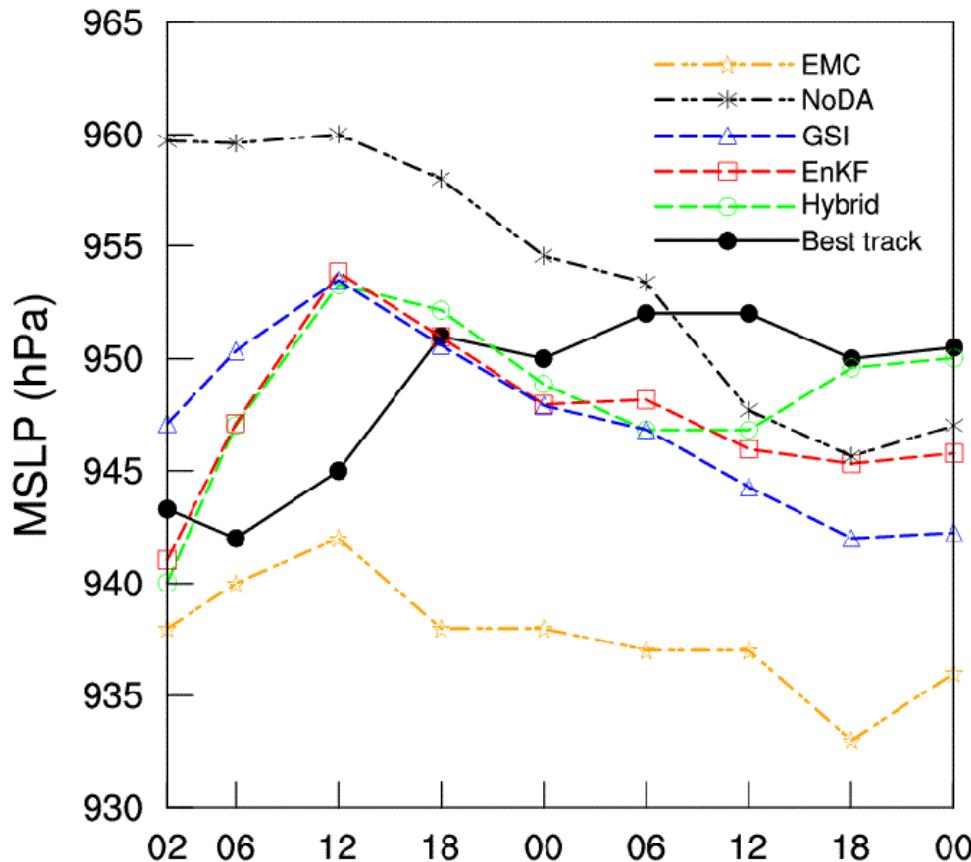
GSI: assimilating TDR using GSI 3DVar

EnKF: assimilating TDR using EnKF

Hybrid: assimilating TDR using hybrid



MSLP forecast



EMC: HWRF official forecast

NoDA: no TDR assimilation

GSI: assimilating TDR using GSI 3DVar

EnKF: assimilating TDR using EnKF

Hybrid: assimilating TDR using hybrid